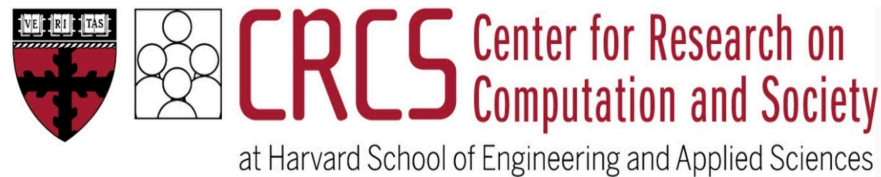




AI for Public Health & Conservation: Learning & Planning in the Data to Deployment Pipeline



MILIND TAMBE
Director, Ctr for Research on Computation & Society
Harvard University



Director “AI for Social Good”
Google Research India

@MilindTambe_AI

AI & Multiagent Systems Research for Social Impact



Public Health



Conservation

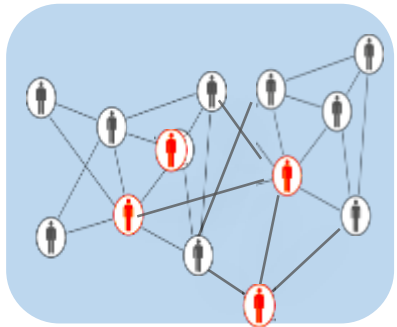


**Public Safety
and Security**

Key Research Challenge

Optimize Our Limited Intervention Resources

Optimizing Limited Intervention Resources



**Social
Networks &
Bandits**

Public Health



**Green
security
games**



Conservation



**Public Safety
& Security**



**Stackelberg
security
games**

Google Research Bangalore

AI for Social Good



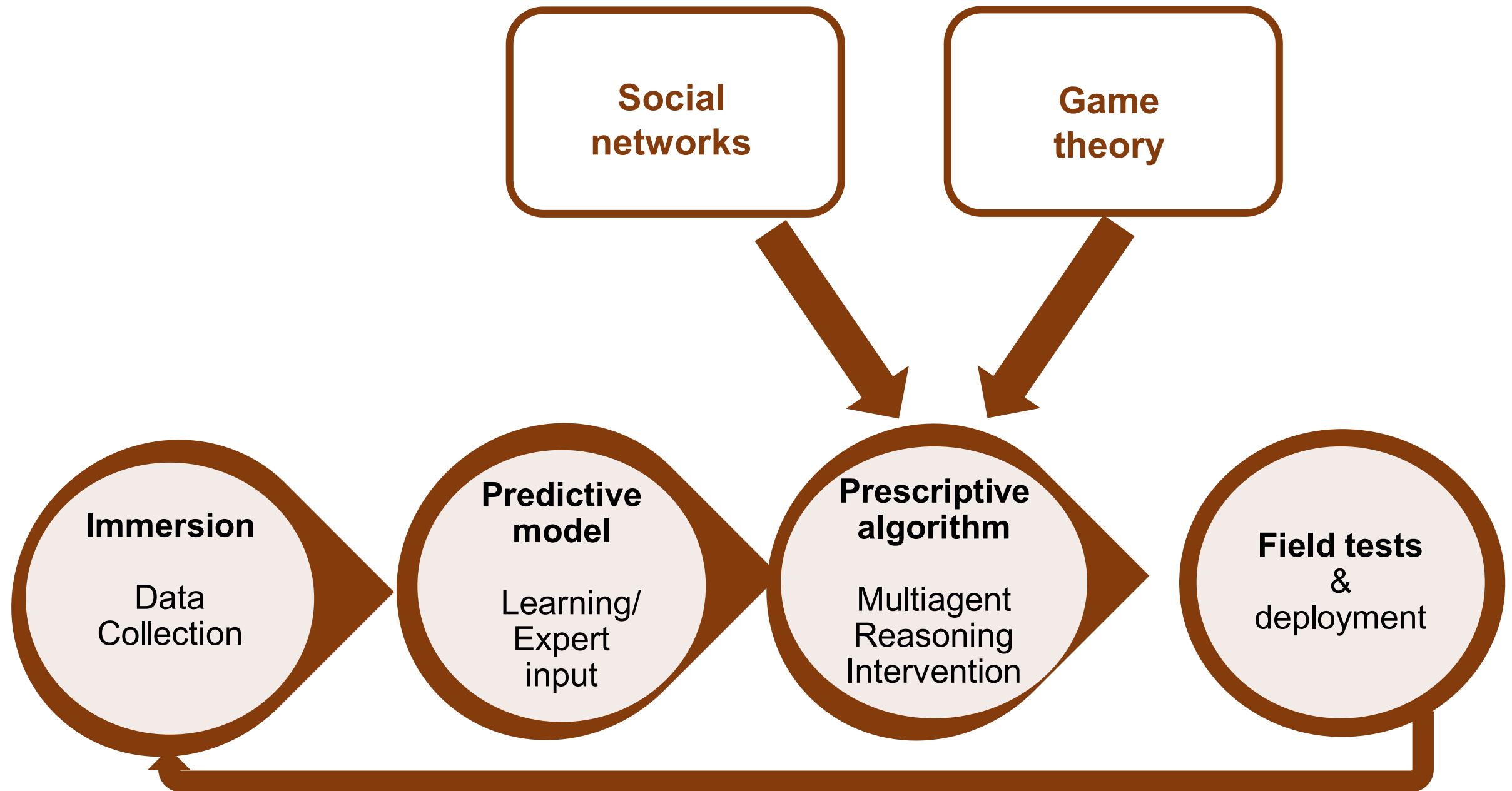
Public Health



Conservation

Three Common Themes

Multiagent systems, Data-to-deployment pipeline, Interdisciplinary partnerships

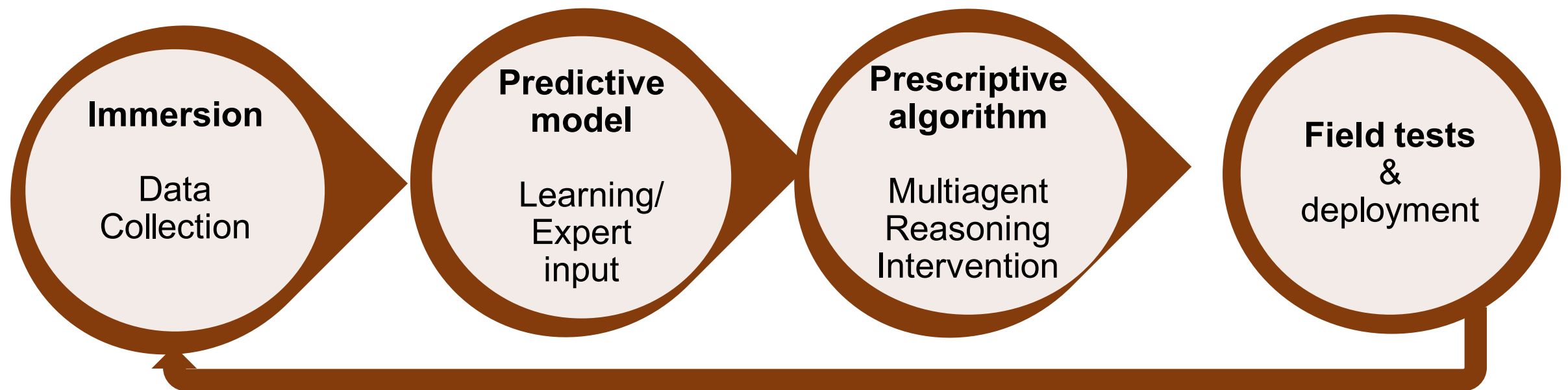


Three Common Themes

Multiagent systems, Data-to-deployment pipeline, Interdisciplinary partnerships

Field test & deployment: Social impact is a key objective

Lack of data is a norm: Must be part of project strategy



Three Common Themes

Multiagent systems, Data-to-deployment pipeline, Interdisciplinary partnerships



Empower non-profits to use AI tools; avoid being gatekeepers to AI4SI technology



ASHOKA TRUST FOR RESEARCH IN
ECOLOGY & THE ENVIRONMENT



Outline



Public Health

- *Information dissemination & behavior change: Social networks*
- *Health program adherence: ML & Bandits*
- *COVID-19: Agent-based modeling*

Conservation

- Cover papers from 2017-now [AAMAS, AAAI, IJCAI, NeurIPS...]
- PhD students & postdocs highlighted

Information dissemination & behavior change

Optimizing Limited Intervention (Social Worker) Resources

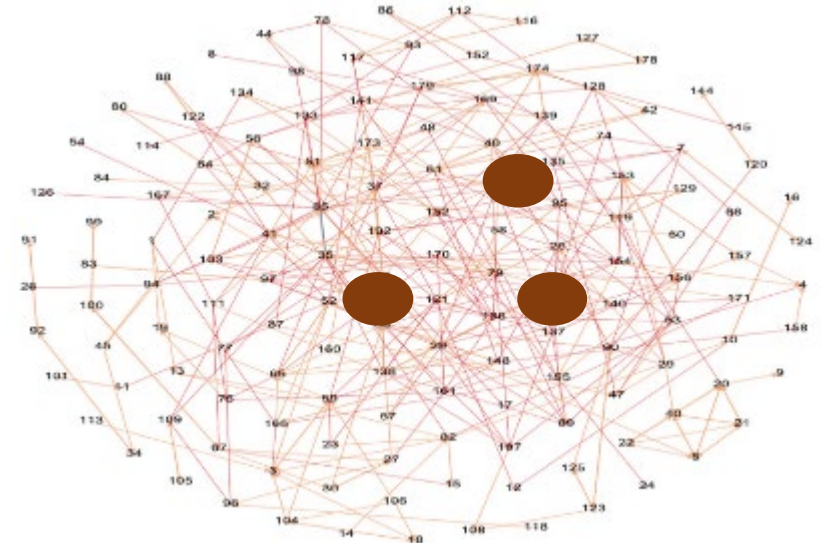
Preventing HIV in homeless youth: Rates of HIV 10 times housed population

- **Shelters:** Limited number of peer leaders to spread HIV information in social networks
- “Real” face-to-face interactions; not Facebook etc



Influence Maximization in Social Networks

- Given:
 - Social network Graph G
 - Choose K “peer leader” nodes
 - Assume: Independent cascade model of information spread
- Objective:
 - Maximize expected number of influenced nodes

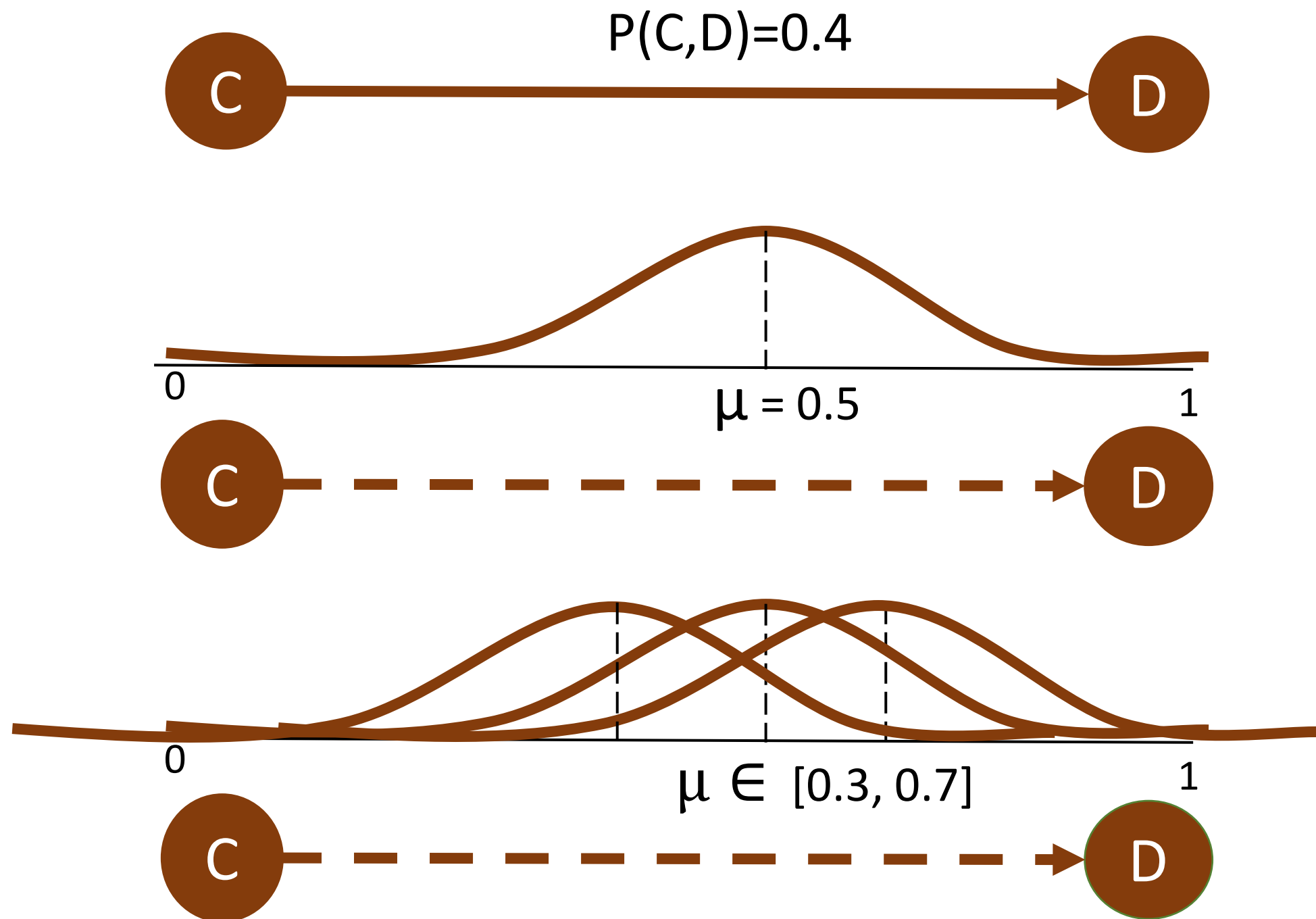


Influence Maximization in Social Networks

Three Key Challenges Combined Together

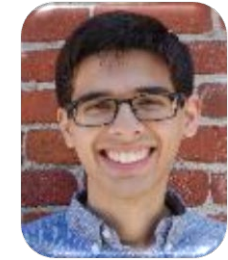
- **Uncertainty in propagation probability over edges**
- **Multi-step dynamic policies to handle peer leader “no shows”**
- **Unknown social network, limited query budget to SAMPLE network**

Challenge 1: Uncertainty in Real-world Physical Social Networks



Robust Influence Maximization

(AAMAS 2017)



Wilder

- Worst case parameters: a zero-sum game against nature

$$\max_{x \in \Delta^{|P|}} \min_{\mu, \sigma} \sum x_p \frac{(\text{Outcome}(p))}{OPT(\mu, \sigma)}$$

Algorithm

Choose Peer Leaders $p \in P$
generating mixed strategy

“ $x \in \Delta^{|P|}$ ”

vs

Nature

Chooses parameters

μ, σ

HEALER Algorithm

Robust Influence Maximization

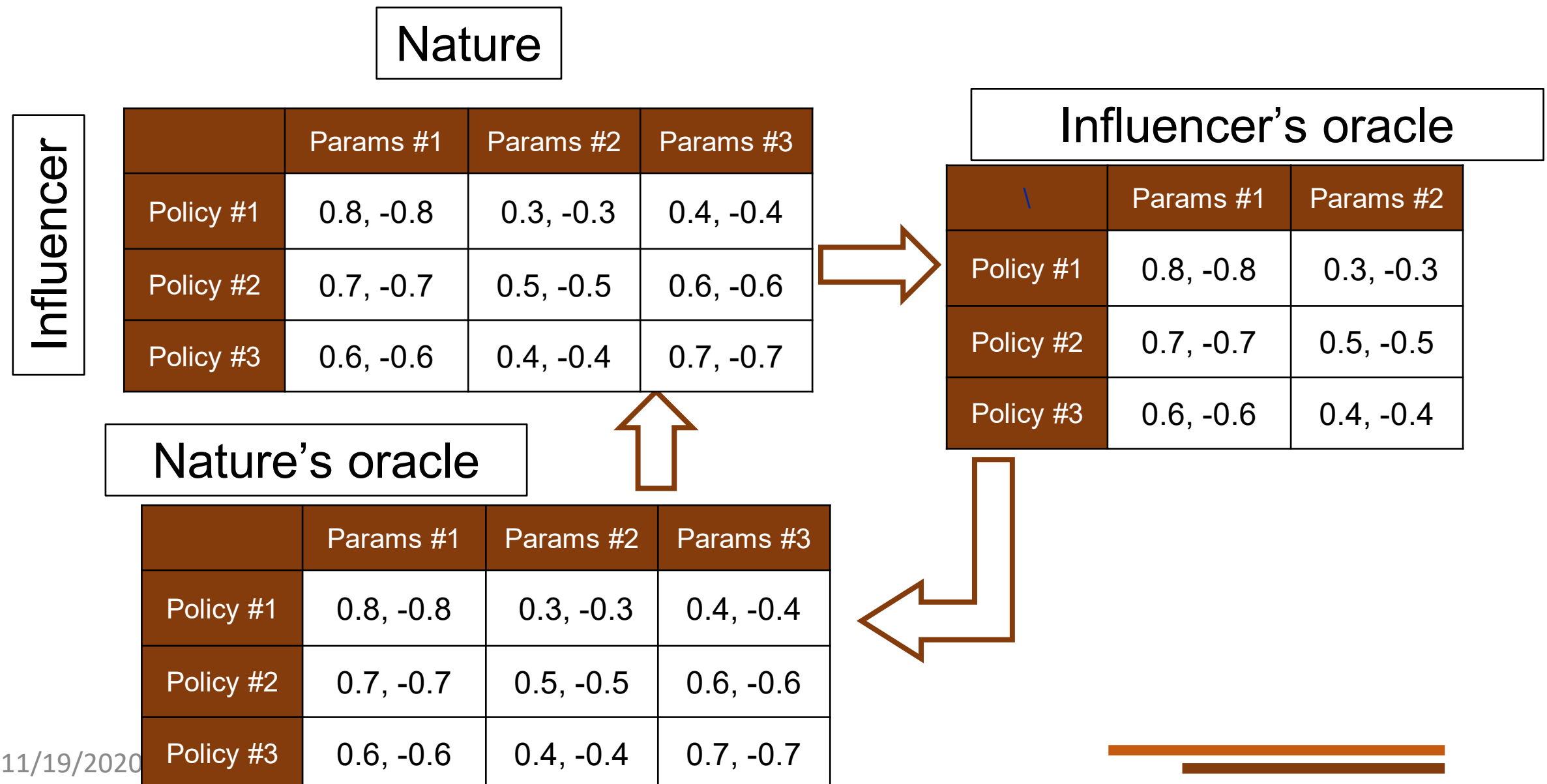
(AAMAS 2017)



Wilder

Theorem: Converge with approximation guarantees

- Equilibrium strategy despite exponential strategy spaces: Double oracle



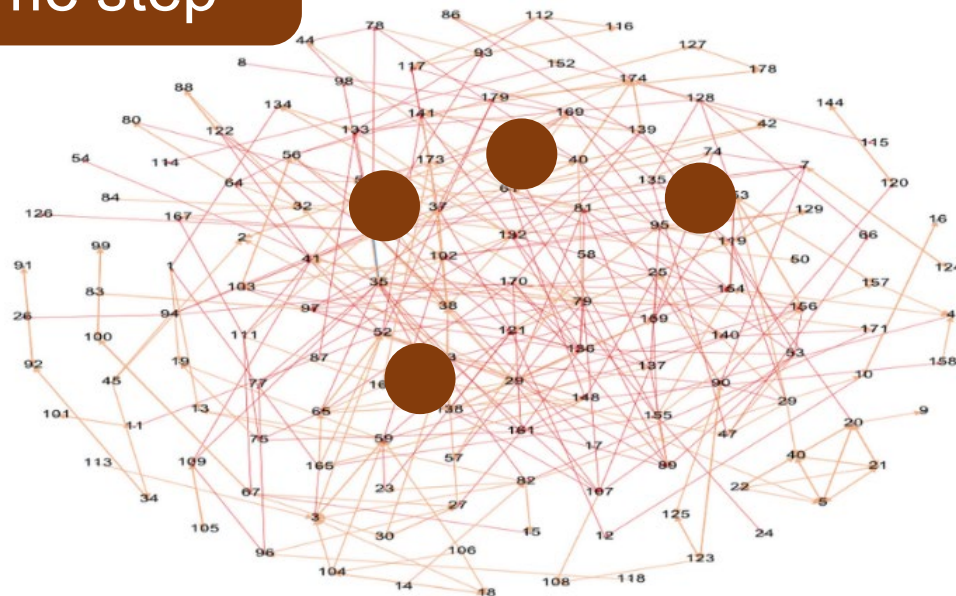
Challenge 2: POMDPs for Multi-step Policy

(AAMAS 2018a)

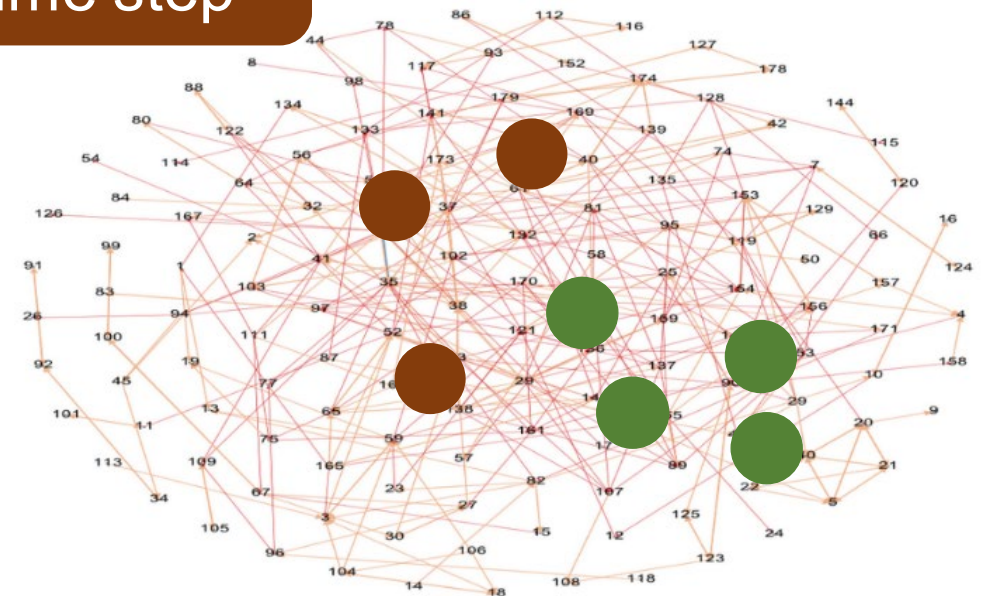


Yadav

$K = 4$
1st time step



$K = 4$
2nd time step

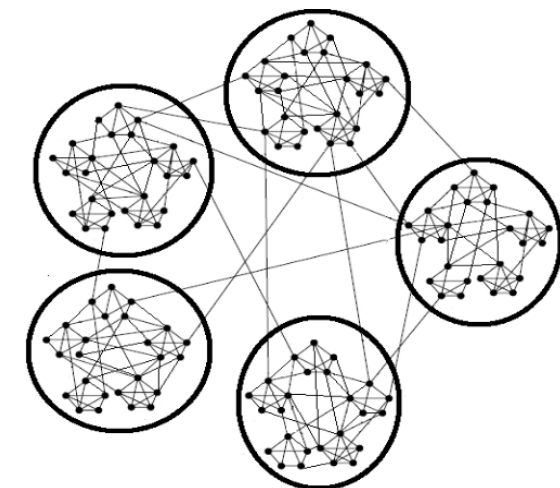


HIDDEN STATE

Action
Choose nodes

POMDP
Policy

Observation: Node presence



Partition POMDPs:
Exploit community structure

Challenge 3: Sampling to avoid Data Collection Bottleneck

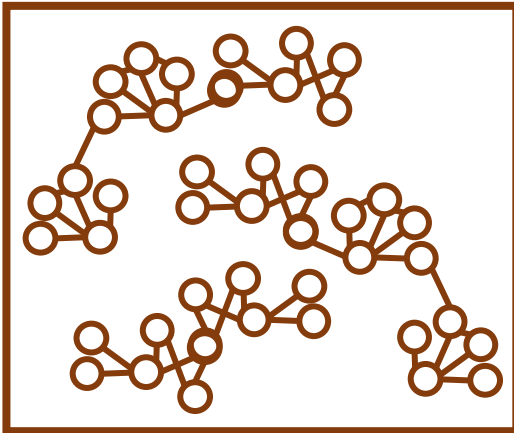
(AAAI 2018)



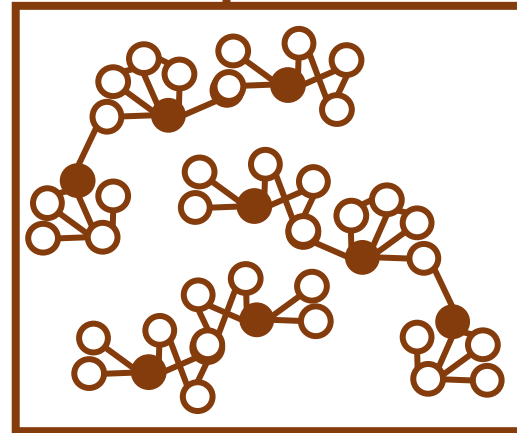
Wilder

Theorem: For community-structured graphs(*), sampling algorithm obtains a constant-factor approximation to the optimal influence spread using $\text{polylog}(n)$ queries.

Data collection costly



Sample 20%



Sampling Algorithm

Sample node randomly
& estimate size of its
community;
Choose seeds from
largest K communities

- Input: total number of nodes, n
- Query upto query budget
- Output K peer leader nodes to spread influence
- Perform similar to OPT , best influence spread with full network

(*)Community structured: drawn from a stochastic block model

Date: 11/19/2020

“Sampling-HEALER”

Pilot tests with 230 Homeless Youth

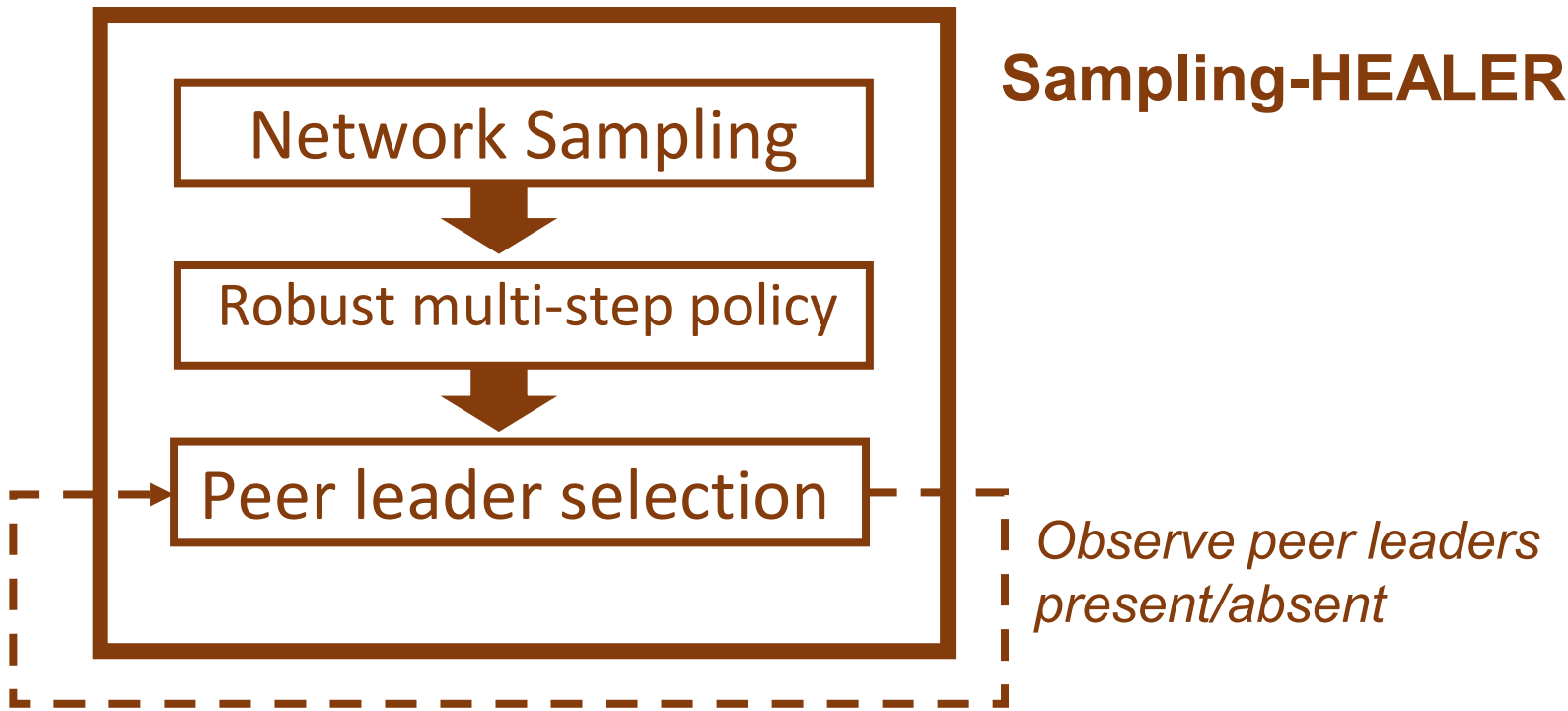
(IJCAI 2018)



Yadav



Wilder



12 peer leaders

Sampling HEALER (Sampled Network)	HEALER (Full Network)	HEALER+ (Full Network)	DEGREE CENTRALITY (Full Network)
60 youth	62 youth	56 youth	55 youth

Results: Pilot Studies

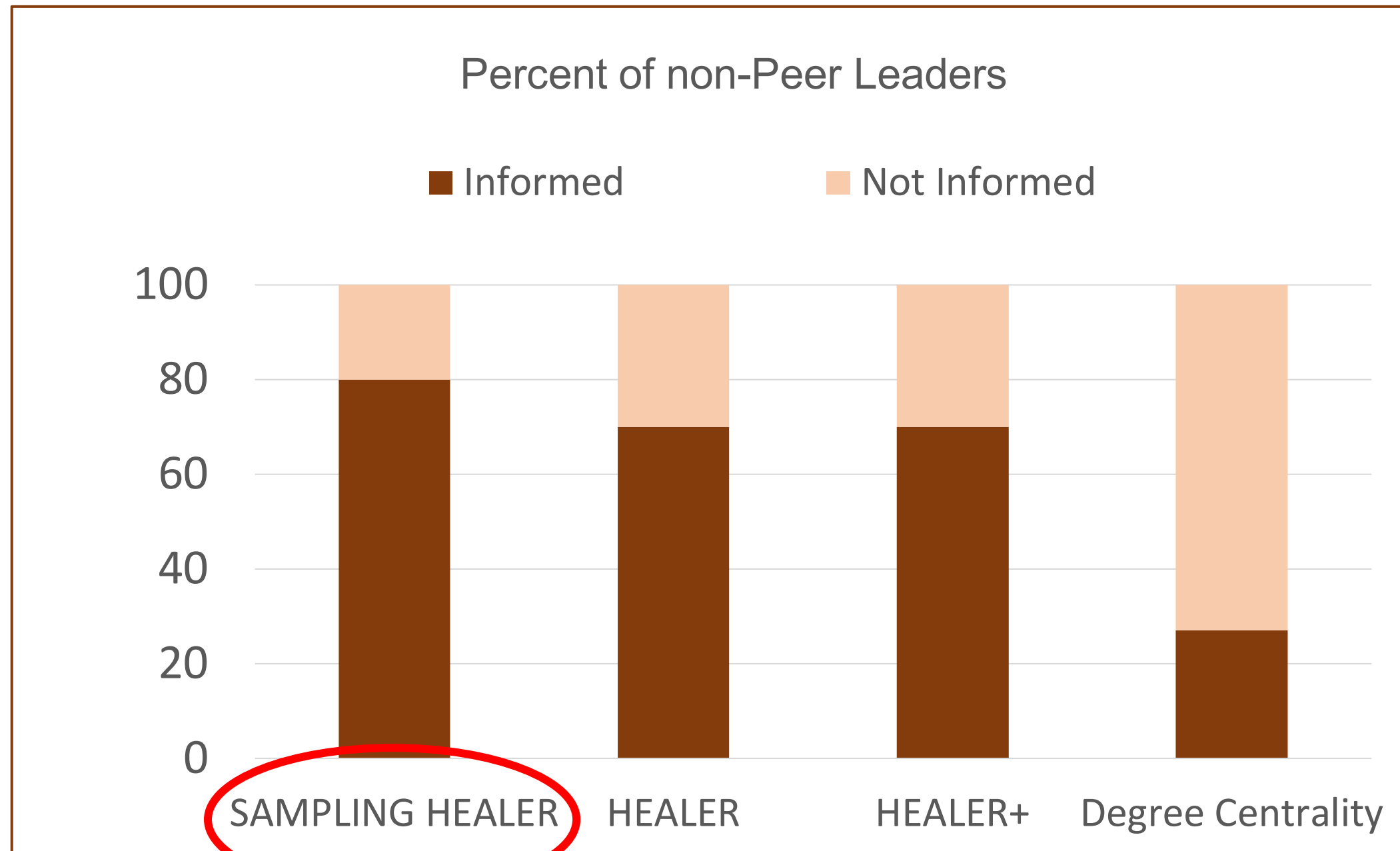
(Journal of Society of Social Work & Research 2018)



Yadav



Wilder



Results of 750 Youth Study [with Prof. Eric Rice]

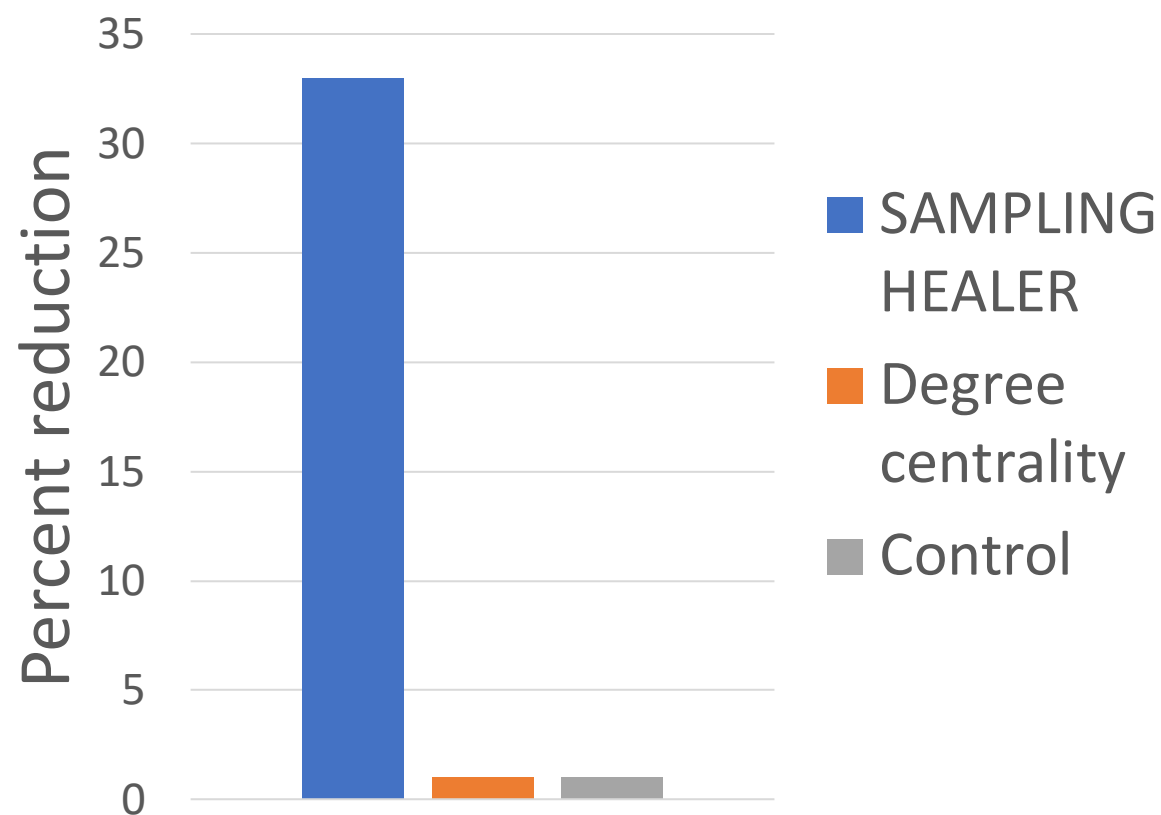
Actual Change in Behavior?

(Under submission)

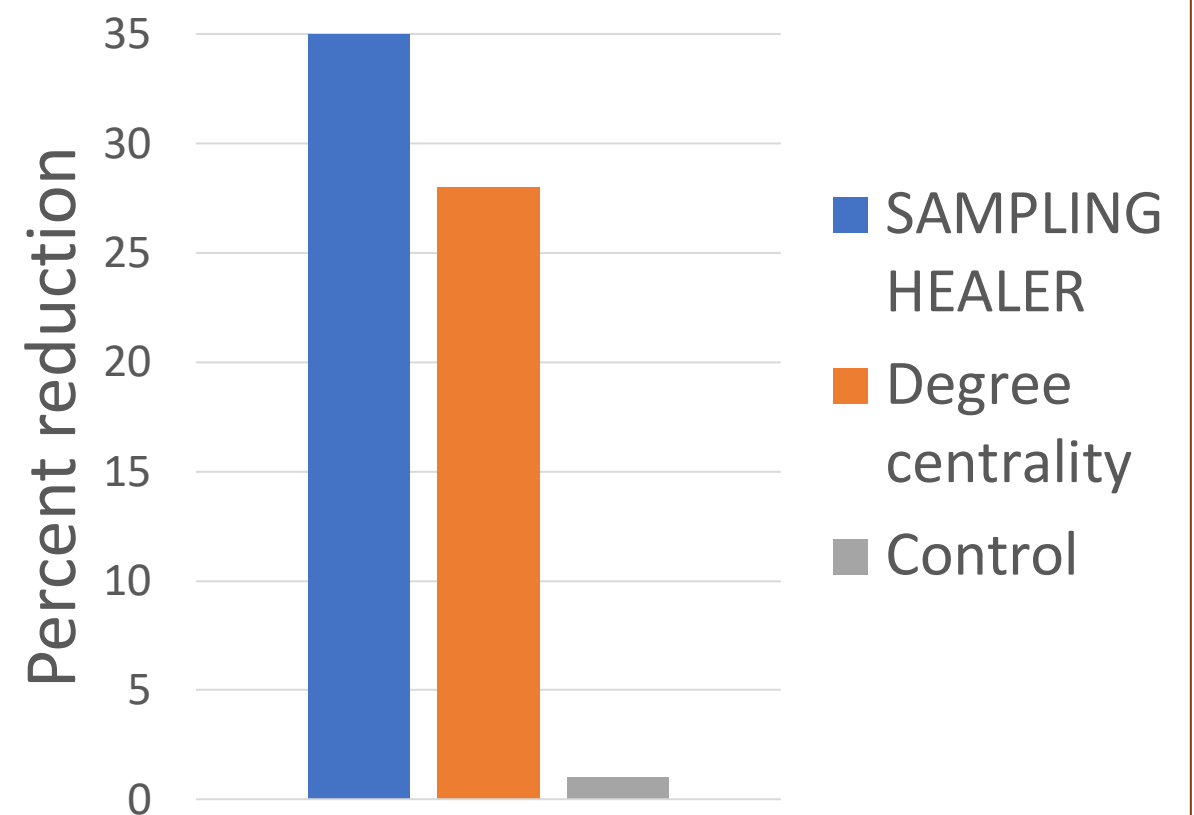
First large-scale application of influence maximization for public health



Reduction in condomless anal sex (1 month)



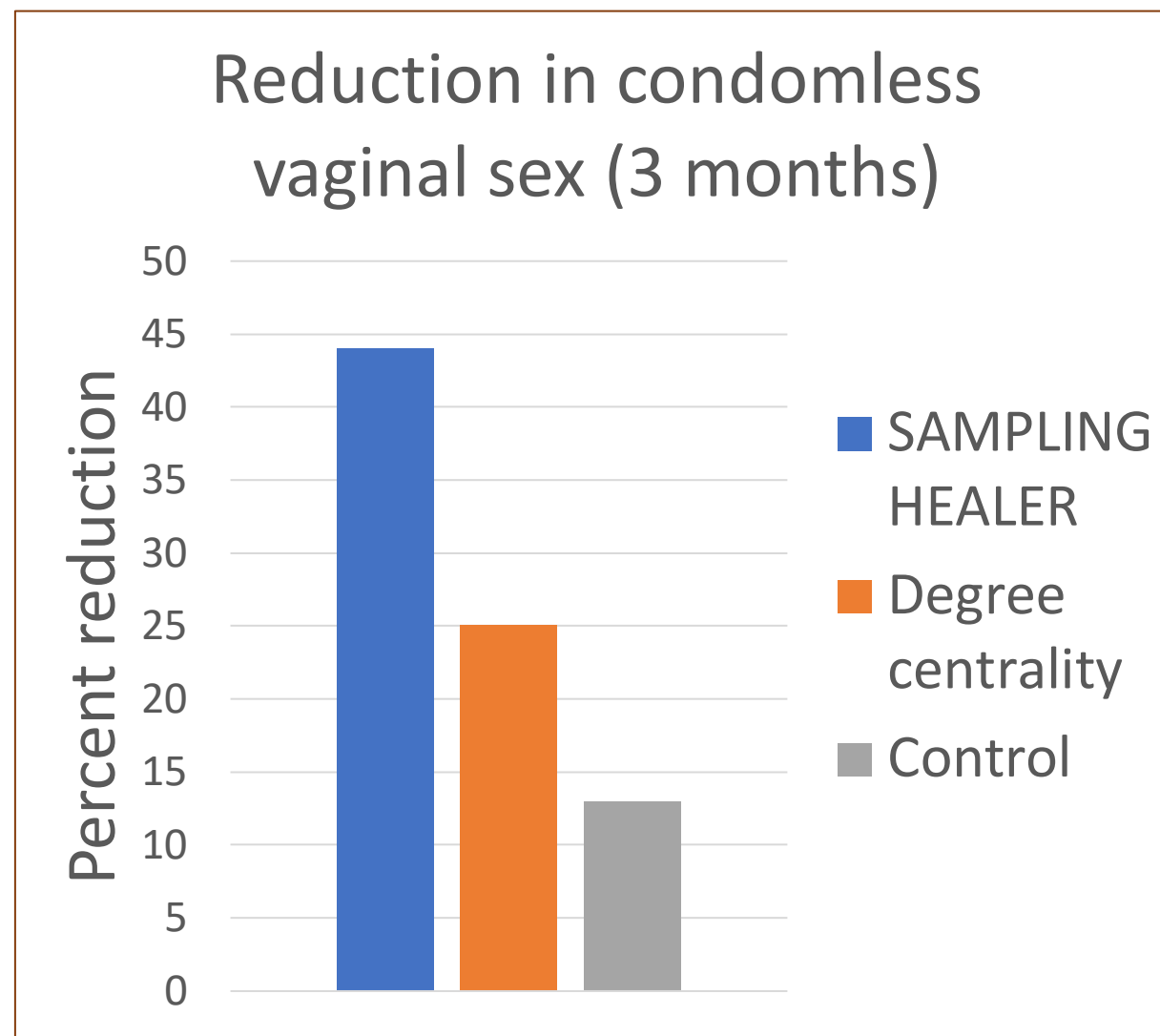
Reduction in condomless anal sex (3 months)



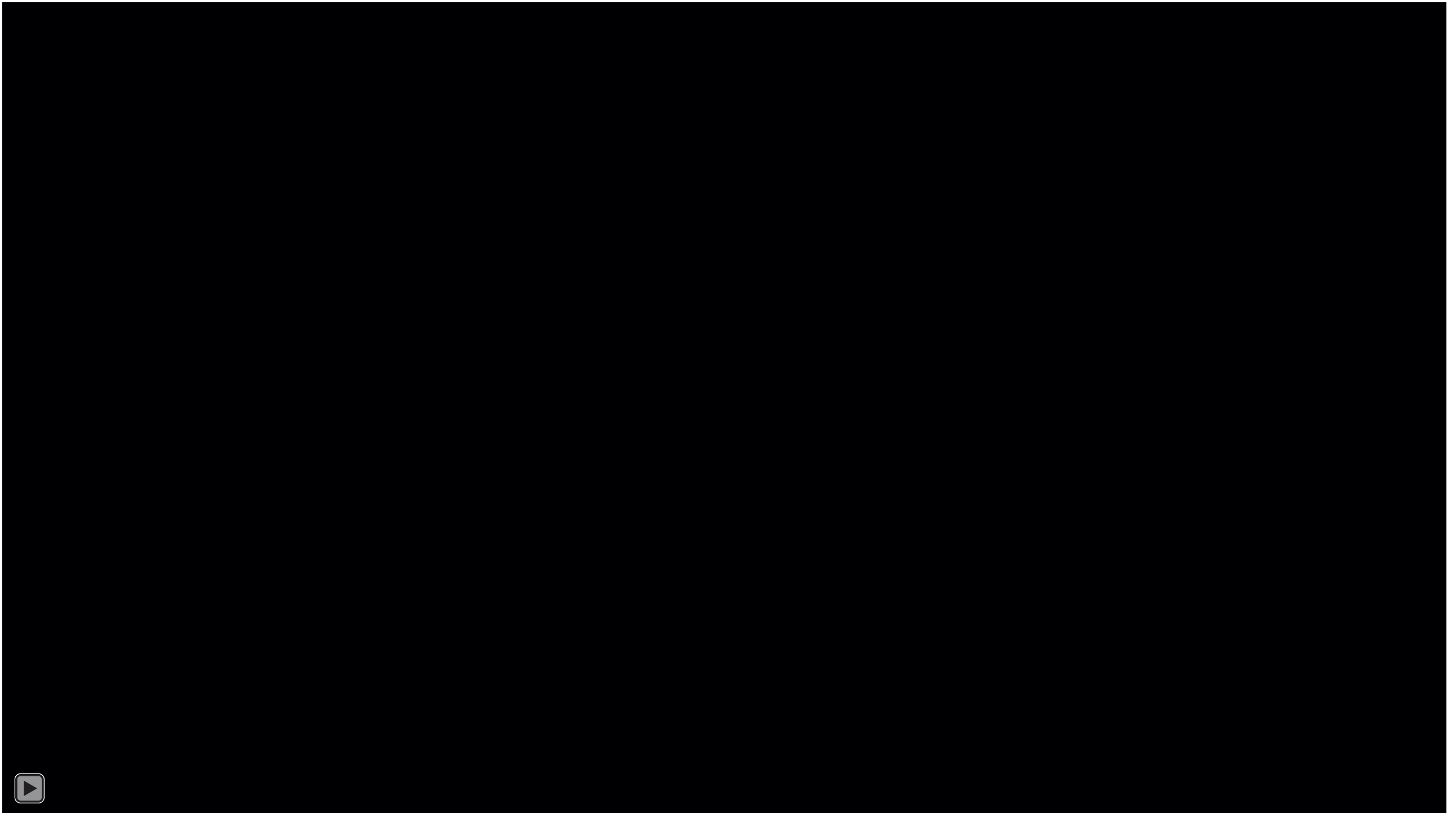
Results of 750 Youth Study [with Prof. Eric Rice]



LOS
ANGELES
LGBT
CENTER

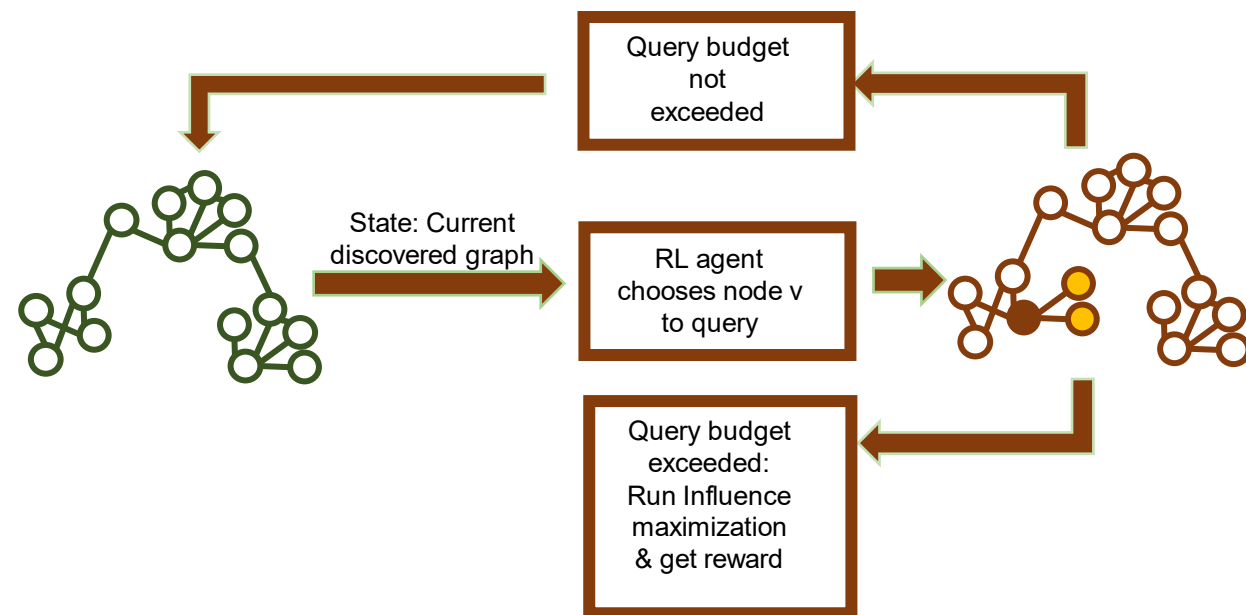


What our collaborators are saying:



Next steps: Data to Deployment Pipeline Using an RL agent?

(with B. Ravindran & team, AAMAS 2020)



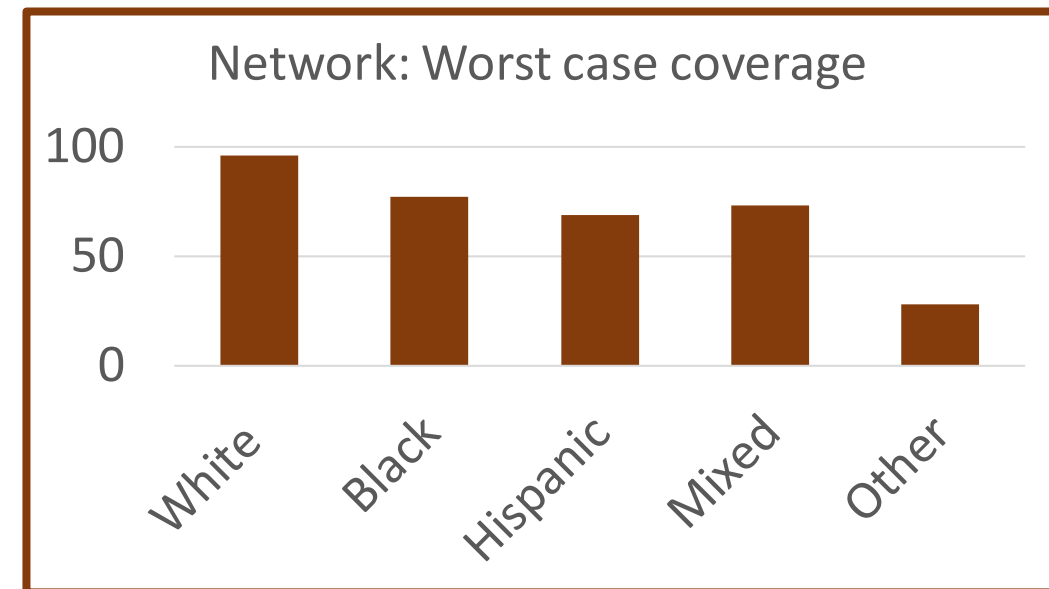
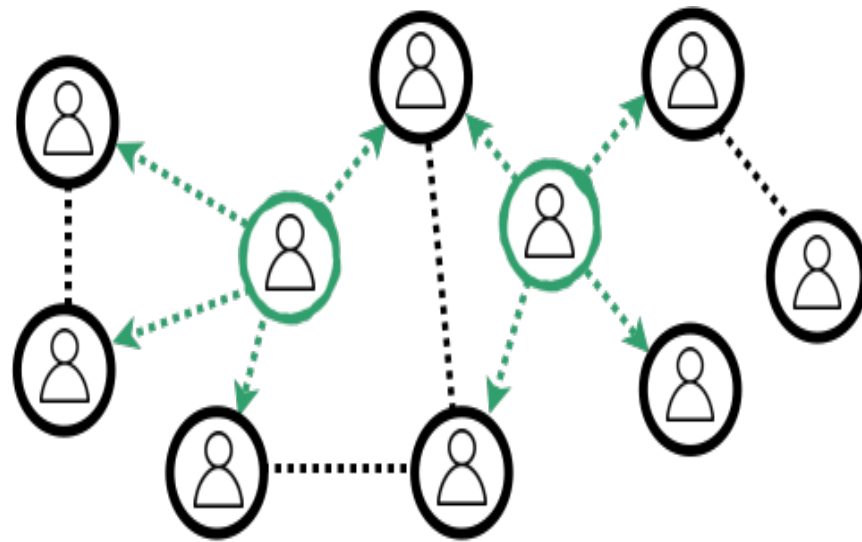
Network Family	Improve %
Rural	23.76
Animal	26.6
Retweet	19.7
Homeless	7.91

Fairness in Reasoning with Social Networks: Suicide Prevention via Gatekeeper Selection

(NeurIPS 2019, IJCAI 2019)



Rahmattalabi



Robust graph covering with gatekeepers, maximize worst case coverage

Disparity in coverage across racial groups

Maxmin fairness: $\min_{c \in C} u_c(A) \geq \gamma$

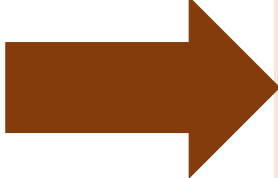
γ : Max of minimum utility for any community

Diversity constraints: $u_c(A) \geq U_c$

U_c : Utility if # gatekeepers allocated proportional to size of community

Outline

Public Health

- 
- *Information dissemination & behavior change: Social networks*
 - *Health program adherence: Passive via ML vs Active via bandits*
 - *COVID-19: Agent-based modeling*

Conservation

Health Program Adherence Maternal & Child Care in India

(Under submission)

India: Woman dies in childbirth every 15 min; 4 of 10 children too thin/short

- *ARMMAN: 18 Million women enrolled, 160000 health workers...*
- *mMitra: Weekly call to new/expectant moms; friendly 3 minute messages about health*
- *mMitra: Significant benefits shown; 2.2 million women enrolled*
- *Unfortunately, significant fraction low-listeners or drop-outs*

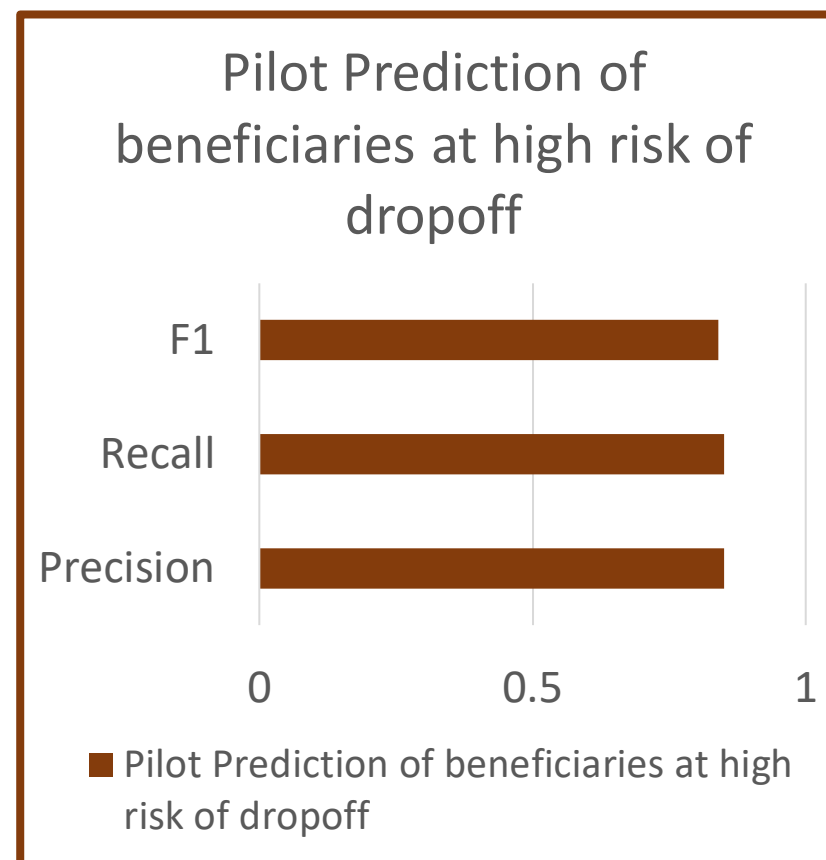
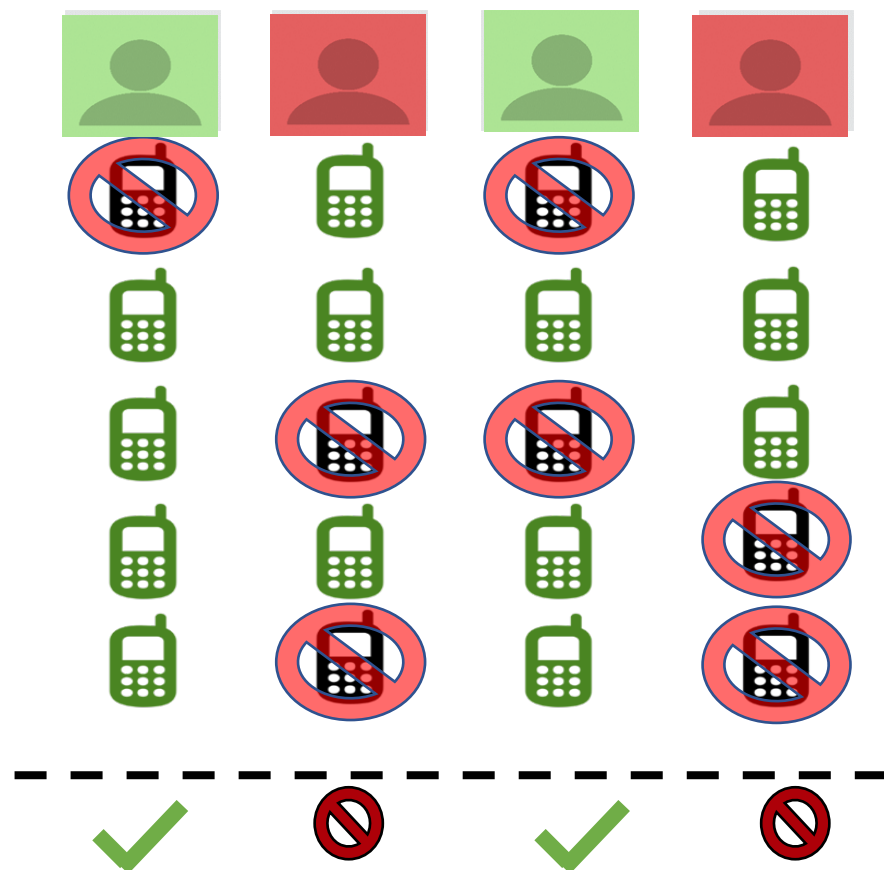


Passive Adherence Monitoring Maternal & Child Care in India

(with B Ravindran IIT Madras)

Predict beneficiaries likely to drop out: Allows ARMMAN to focus intervention

- Neural networks for prediction: Extensive tests with past data
- Results of pilot with 18000 beneficiaries: High precision, recall, accuracy
- **Prediction software deployed: helps 300,000 beneficiaries in mMitra**



ARMMAN Pilot

- 18000 Beneficiaries
- Nov & Dec 2019
- Test: Jan-April 2020

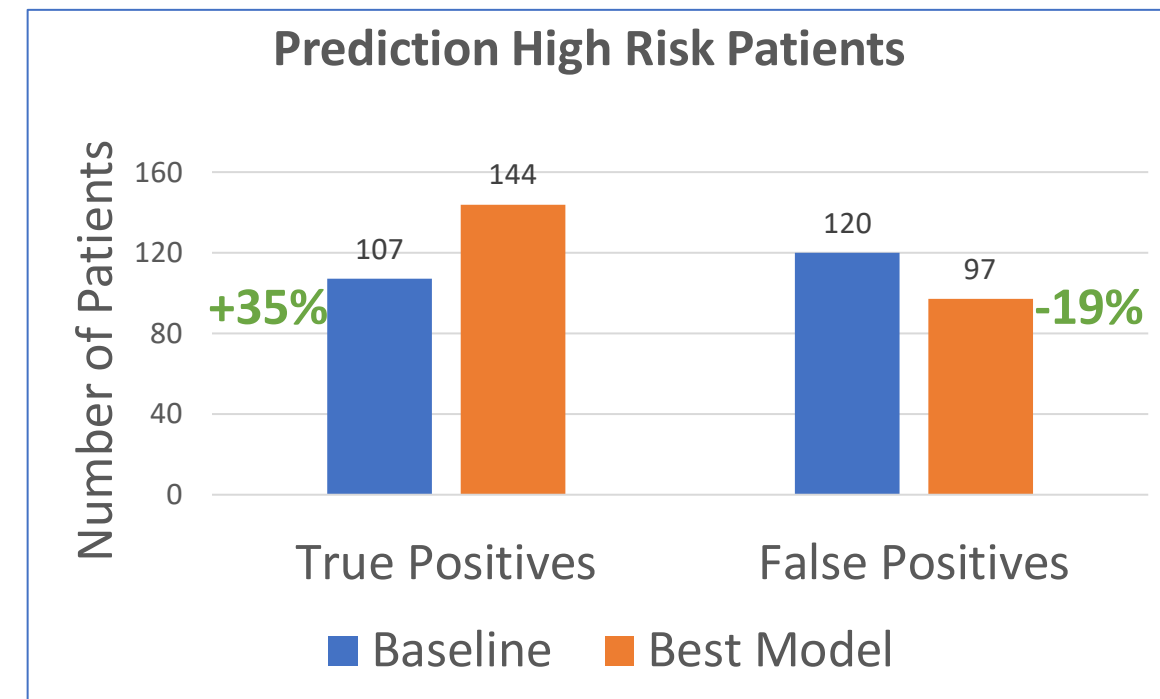
Passive Adherence Monitoring Preventing Tuberculosis in India

(KDD 2019)

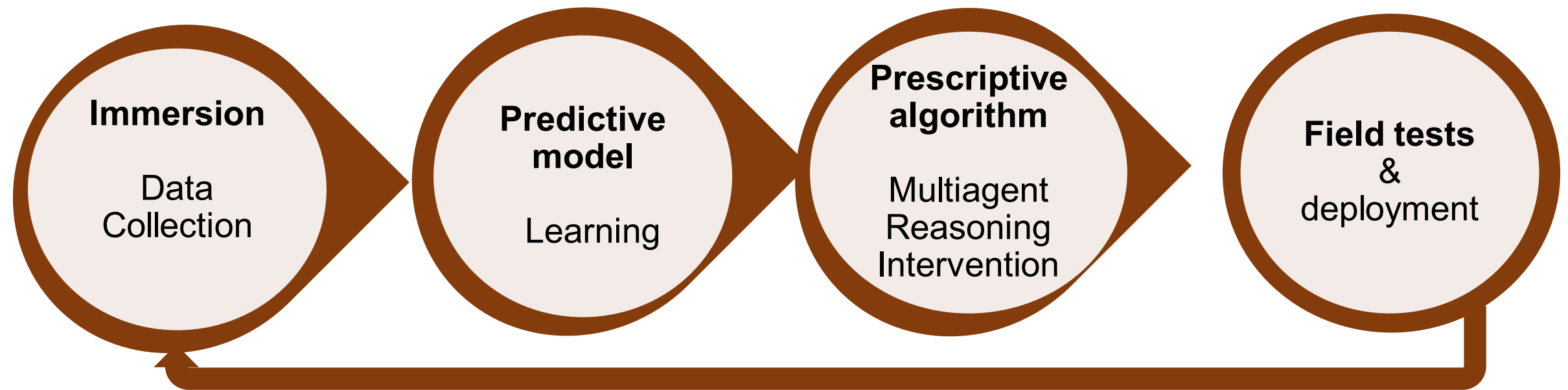


Tuberculosis (TB): ~500,000 deaths/year, ~3M infected in India

- *Non-adherence to TB Treatment: Digital adherence tracking via daily phone calls*
- *Intervene before patients miss dose*
- *Predict adherence risk from phone call patterns?*
- *Results from Mumbai, India: 15,000 patients, 1.5 million phone calls*



Intervention Reasoning: Active Adherence Monitoring



Intervention Scheduling with Scarce Data: Active Adherence Monitoring

(NeurIPS 2020)



Mate



Killian

Health worker intervention

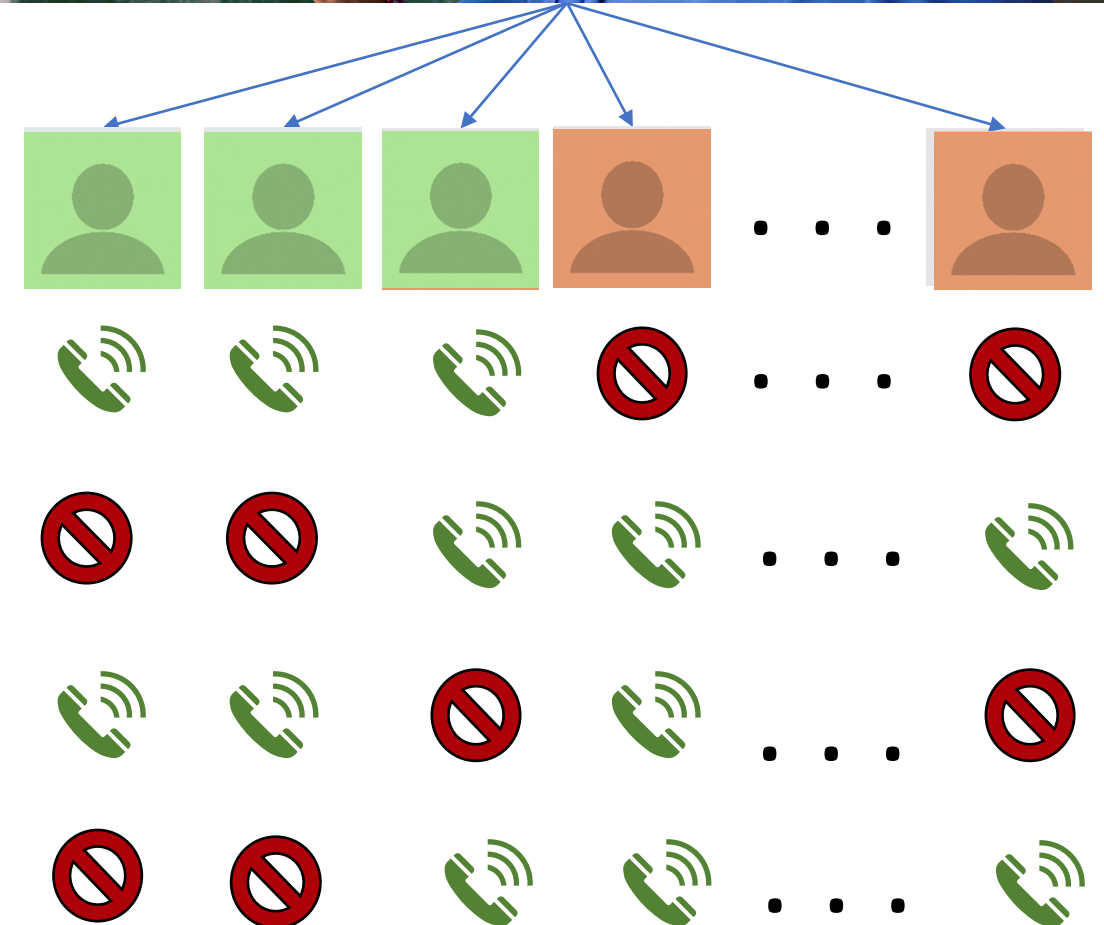
Call patients: Track, improve adherence

Challenge:

- Large number of patients (N)
- Which ' k ' patients to call?

Approach:

- Adherence Restless Bandits



Intervention Scheduling with Scarce Data: Adherence Restless Bandits(A-RMAB)

(NeurIPS 2020)



Mate



Killian

Restless multiarmed bandits (RMAB)

Adherence RMAB (A-RMAB):

- Each arm (patient): binary latent state $\{0, 1\}$
- 0= not-adhering; 1= adhering

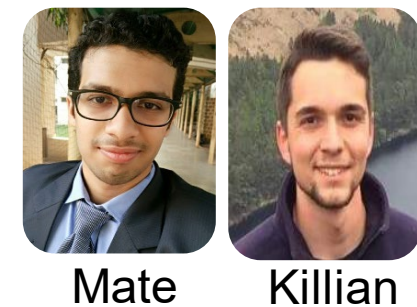
	not-adhering	adhering
not-adhering	0.90	0.10
adhering	0.05	0.95

Patient state may be not observed:

- Belief state (i.e., probability) of adherence

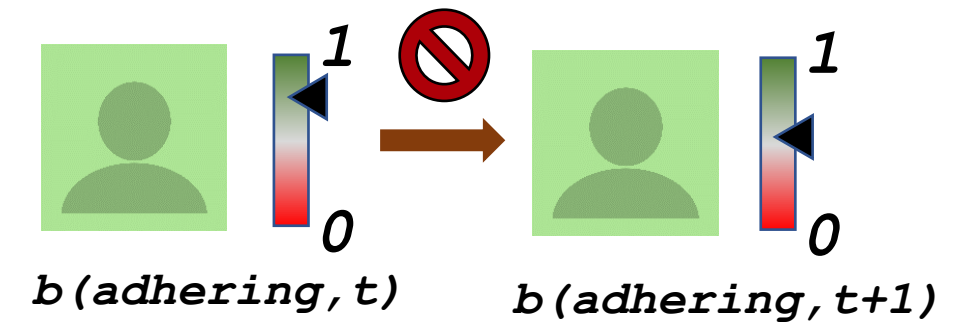


Intervention Scheduling with Scarce Data: Adherence Restless Bandits(A-RMAB)



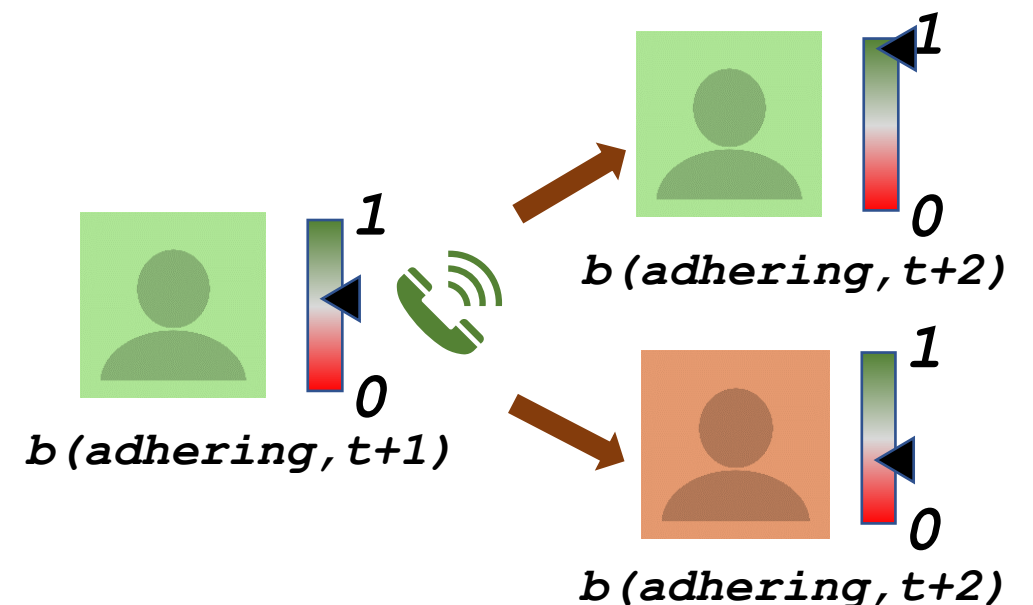
When arm not played

- No observation
- Instead, compute belief of adherence



When arm is played

- Observe current state
- Higher chance of adhering next round



Could convert into a giant POMDP & solve: but inefficient

Adherence Restless Bandits(A-RMAB): Whittle Index



Mate



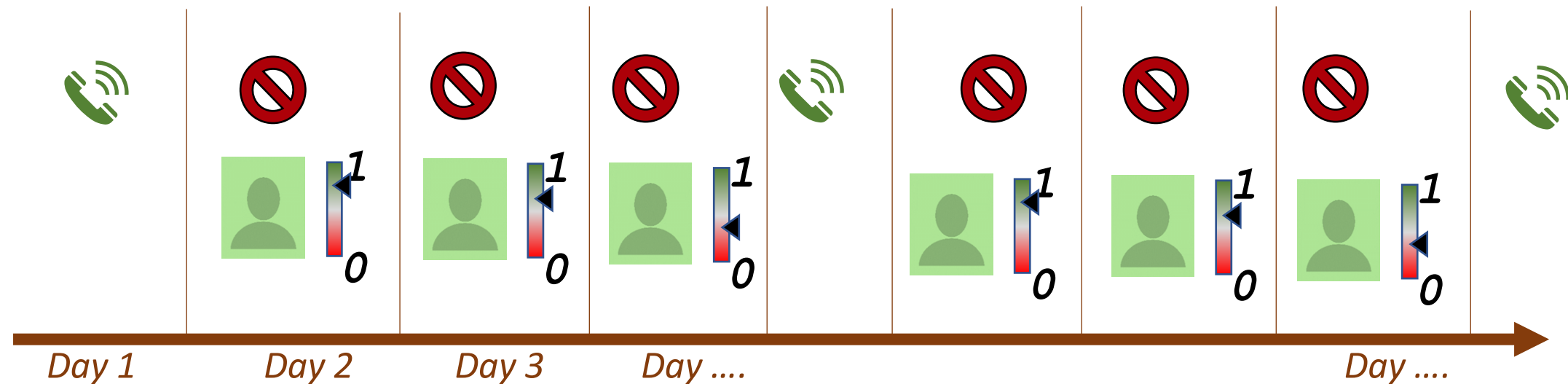
Killian

- *Performance guarantee requires A-RMAB to be indexable*

Theorem 1: A-RMAB Indexable if threshold policies are optimal.

- *Threshold policies: Forward Threshold*

Call → Belief of adherence below threshold → Call



- *Exploiting threshold policies allow for a fast algorithm*

Intervention Scheduling with Scarce Data: Adherence Restless Bandits(A-RMAB)

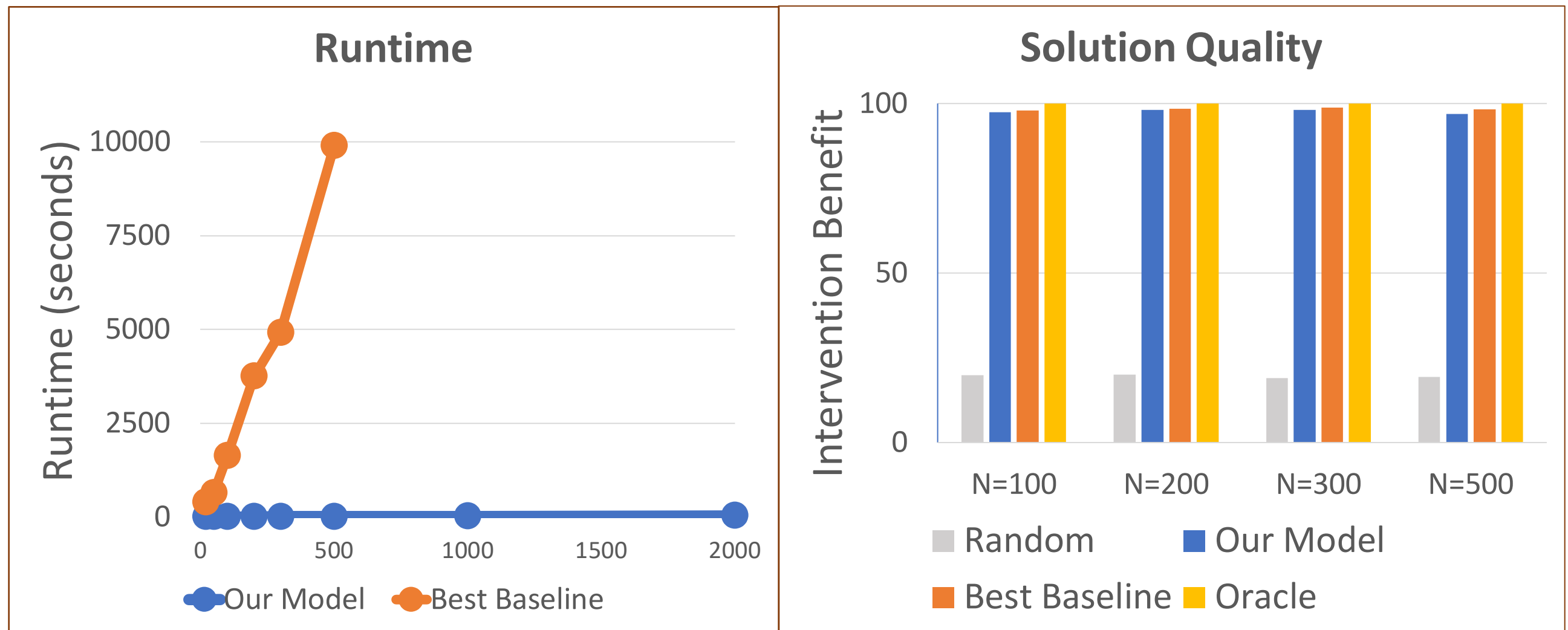


Mate



Killian

- *Orders of magnitude speedup with no solution quality loss*
- **ORANGE** = *Best baseline*
- **Blue** = *Our model*



Outline

Public Health

- *Information dissemination & behavior change: Social networks*
- *Health program adherence: Passive via ML vs Active via bandits*
- *COVID-19: Agent-based modeling*

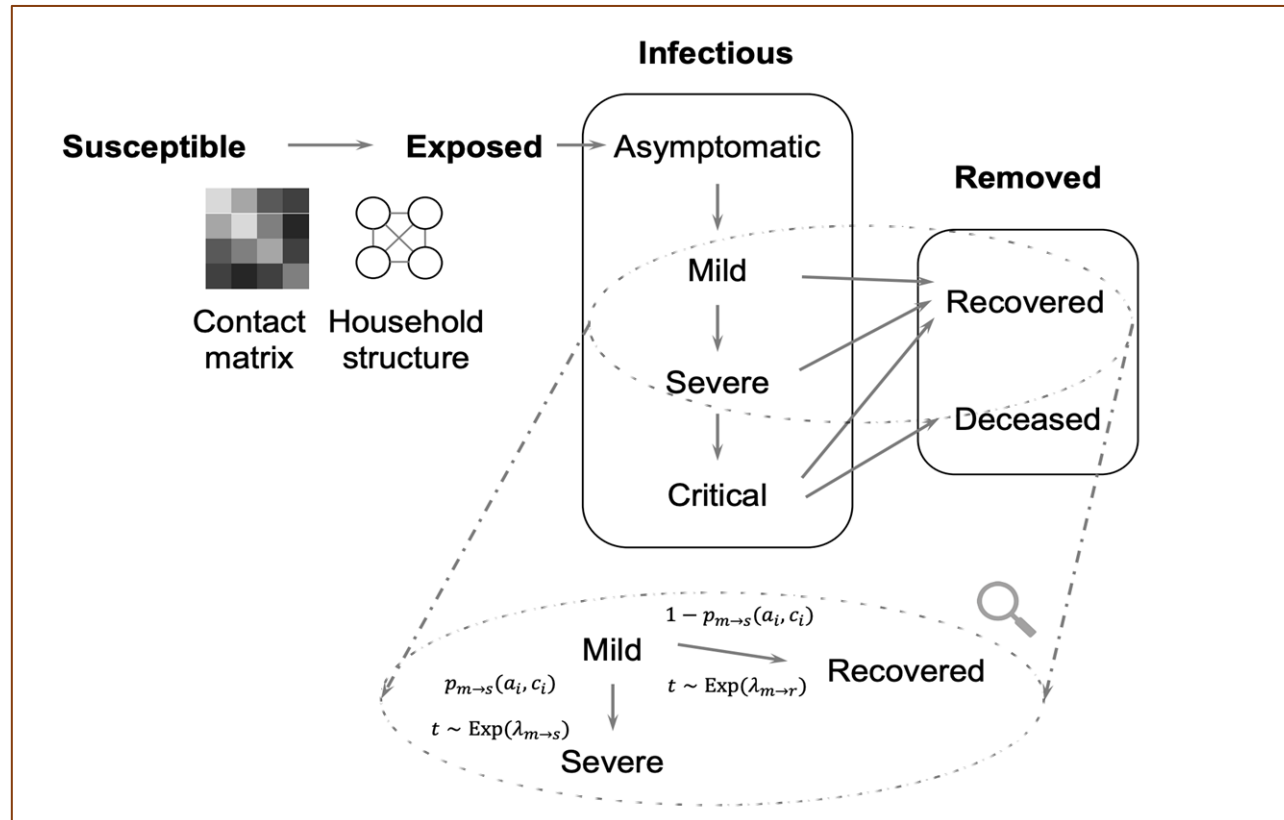
Conservation

COVID-19: Agent-based Simulation Model

(*Proceedings National Academy of Sciences*, 2020)



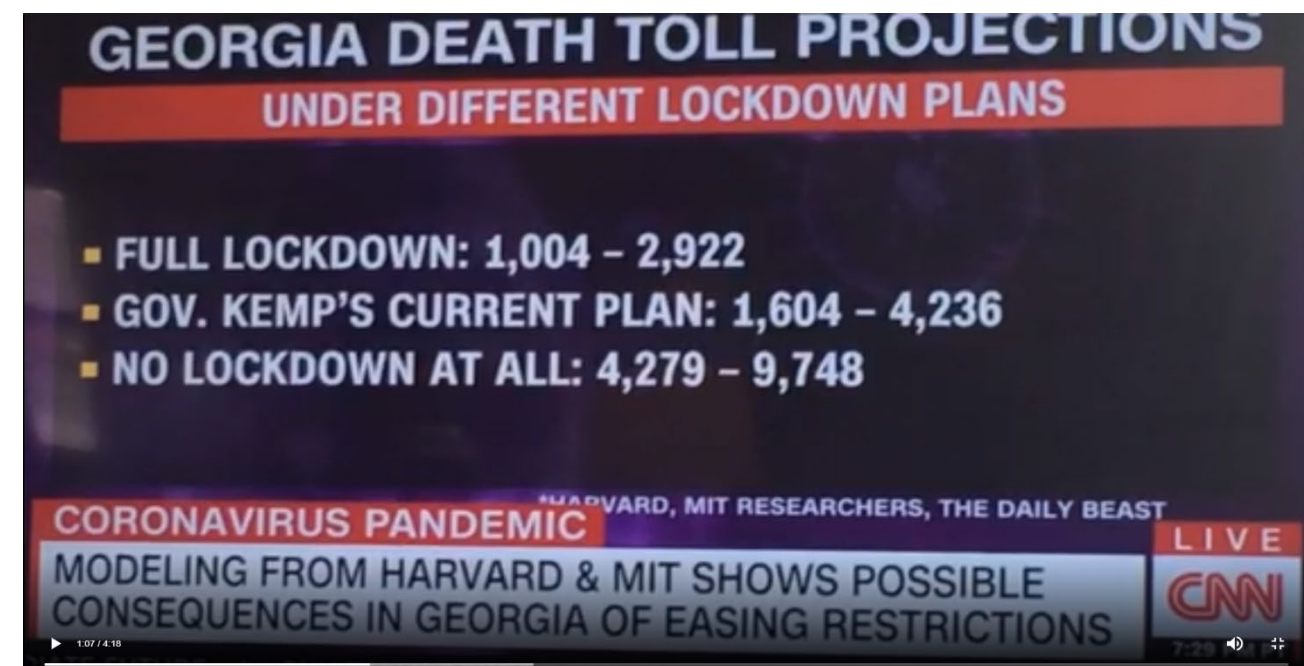
Wilder



Agent-based model:

- Families
- Co-morbidities
- Age
- Testing
- Contact tracing

New Model Shows How Deadly Lifting Georgia's Lockdown May Be



COVID Testing Policy: Accuracy vs Ease

(*Science Advances*, 2020)



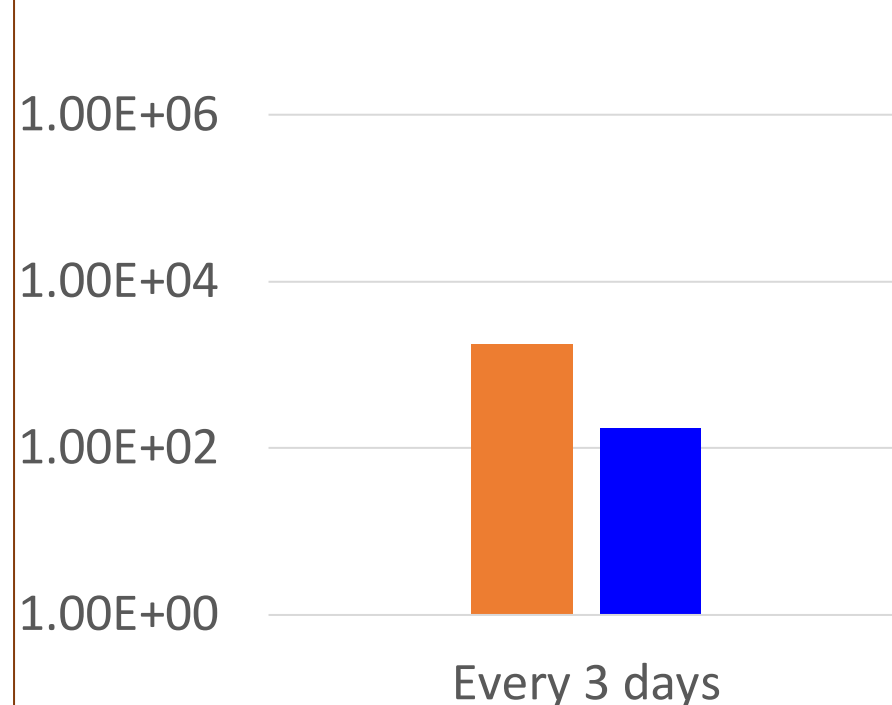
Wilder

- Range of tests entering market, varying sensitivity/cost: Quantity vs Quality?
 - qRT-PCR (“gold standard”): Detect viral concentration of 10^3 /mL, \$50-100
 - RT-LAMP: 10^5 /mL, \$5-30
 - Antigen strip (“Less sensitive”): 10^6 /mL, \$3-5

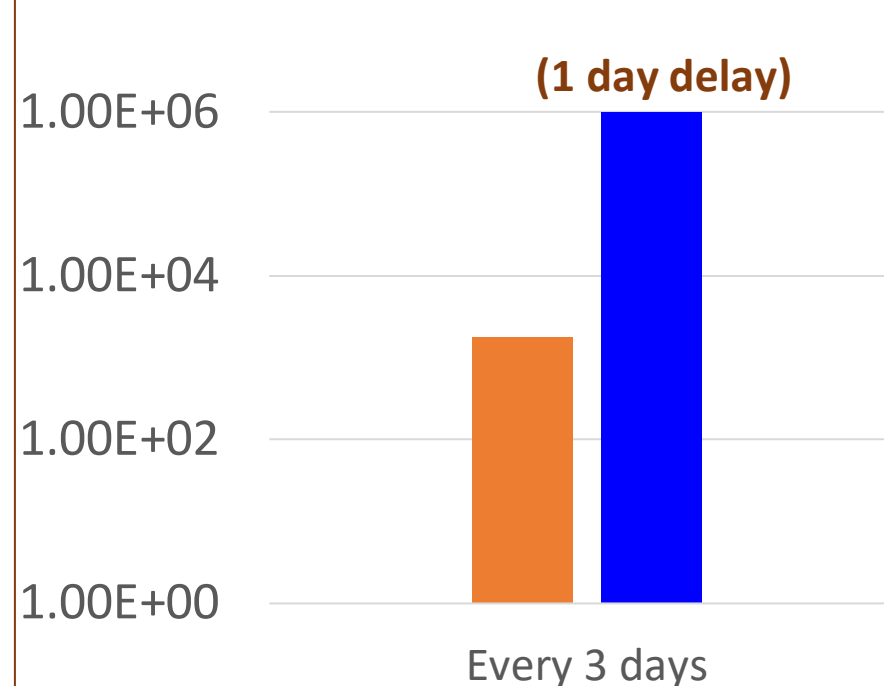
Test sensitivity is secondary to turnaround time & frequency for COVID-19 surveillance

 Less sensitive; Cheap & fast turnaround  More sensitive; Costly & slow turnaround

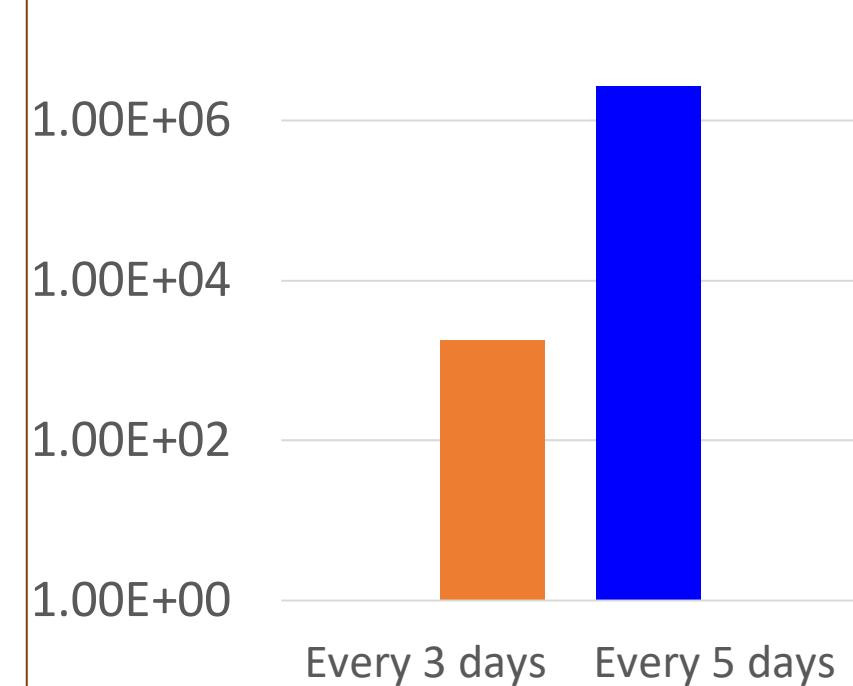
Total infections



Total infections



Total infections

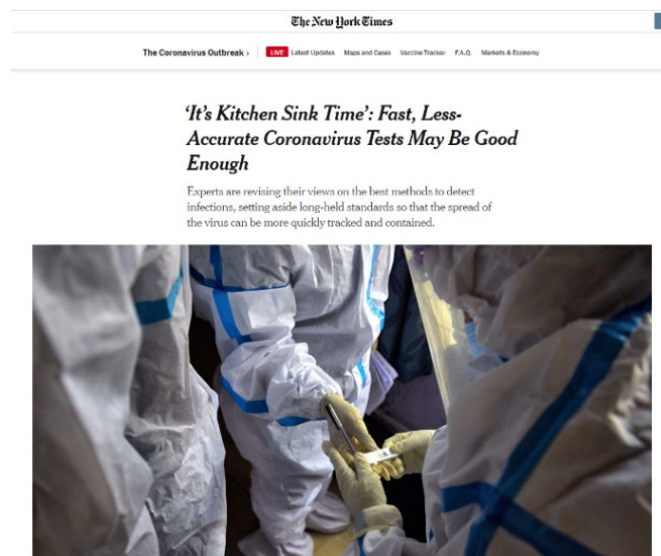


COVID Testing Policy: Impact

- WHO guidance reference
- Covered in NYT, WaPo, Time, The Atlantic, The Hill, etc
- Allowed epi collaborators to advocate to FDA/CDC

Diagnostic testing for SARS-CoV-2

Interim guidance
11 September 2020



Outline

Public Health



Conservation

- *Protect wildlife, forests, fisheries: Game-focused learning*
- *Integrating real time data for protection: Signaling games*

Protecting Conservation Areas: Green Security Games

(IJCAI 2015)



Fang



Snare or Trap

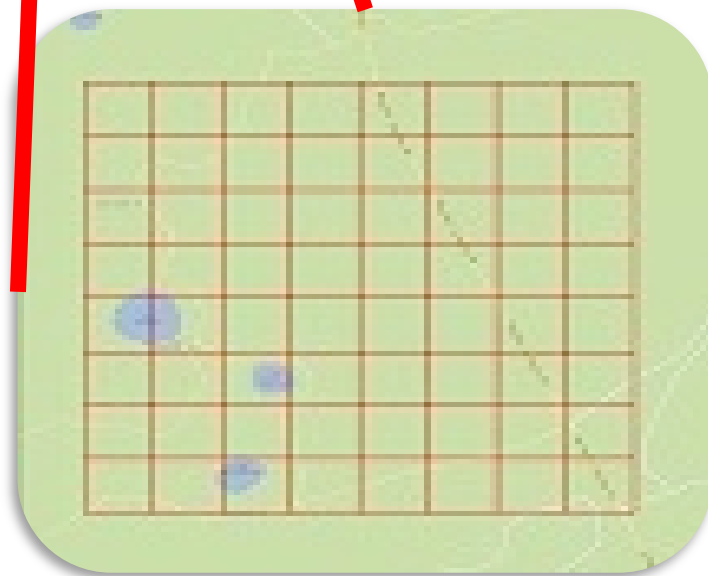


Wire snares



From Stackelberg Security Games to Green Security Games

(IJCAI 2015)



- *Stackelberg security games (SSG)*
- *With boundedly rational poachers*
- *Learn adversary response model at targets “i”*



	Area1	Area2
Area1	4, -3	-1, 1
Area2	-5, 5	2, -1

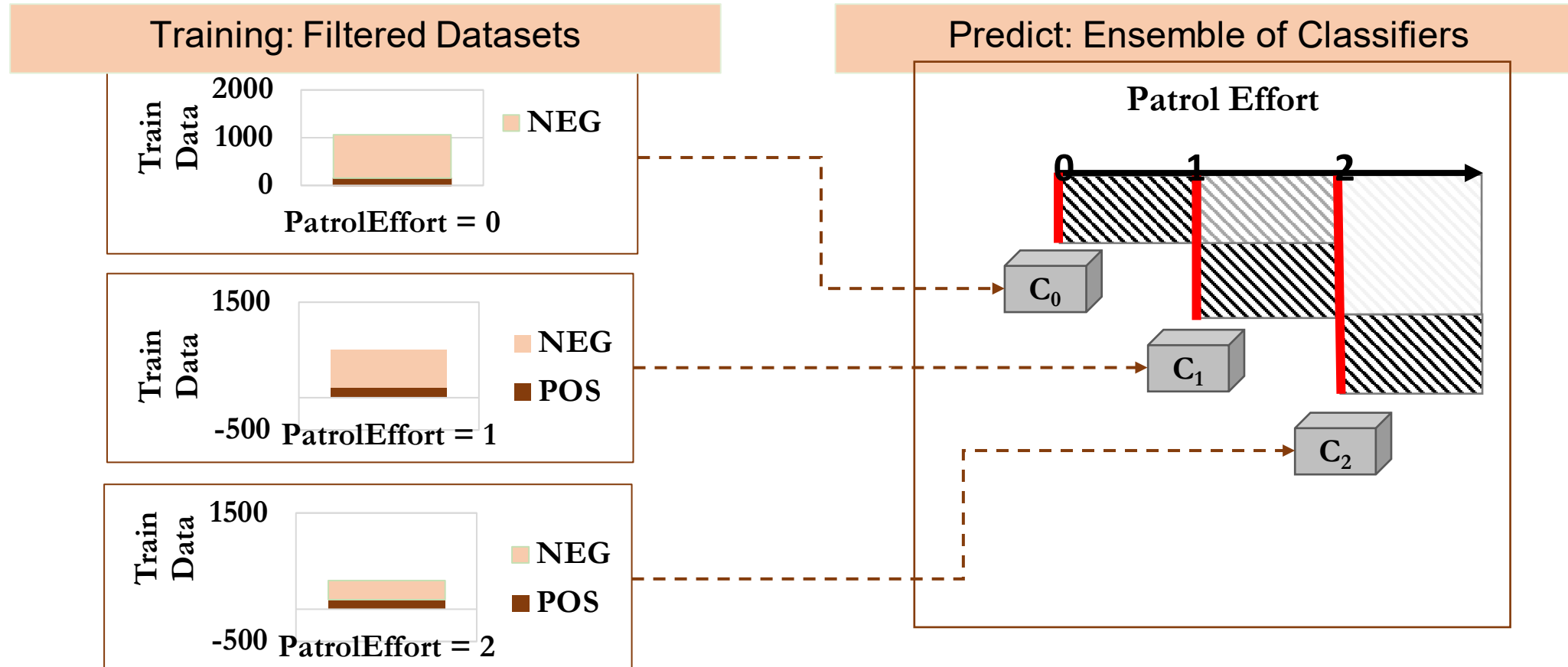
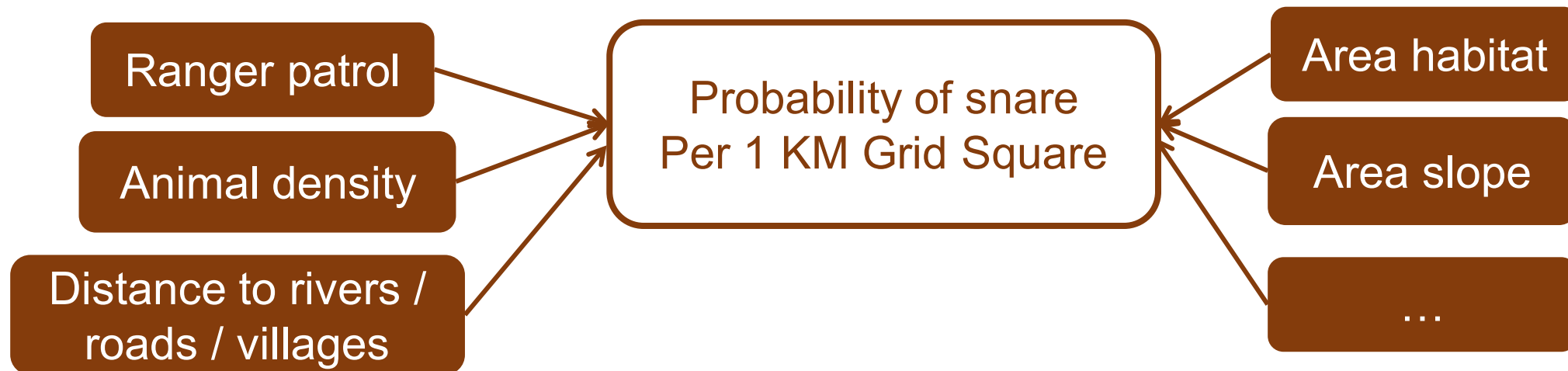
Learning Adversary Response Model: Uncertainty in Observations



Nguyen



Gholami



PAWS: First Pilot in the Field

(AAMAS 2017)



Ford

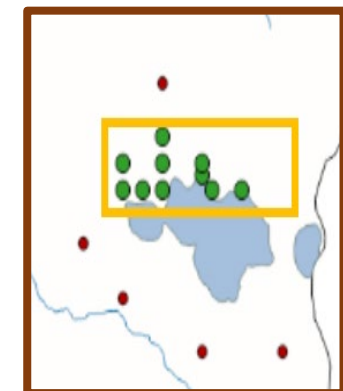
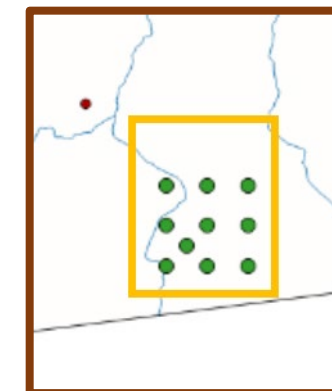
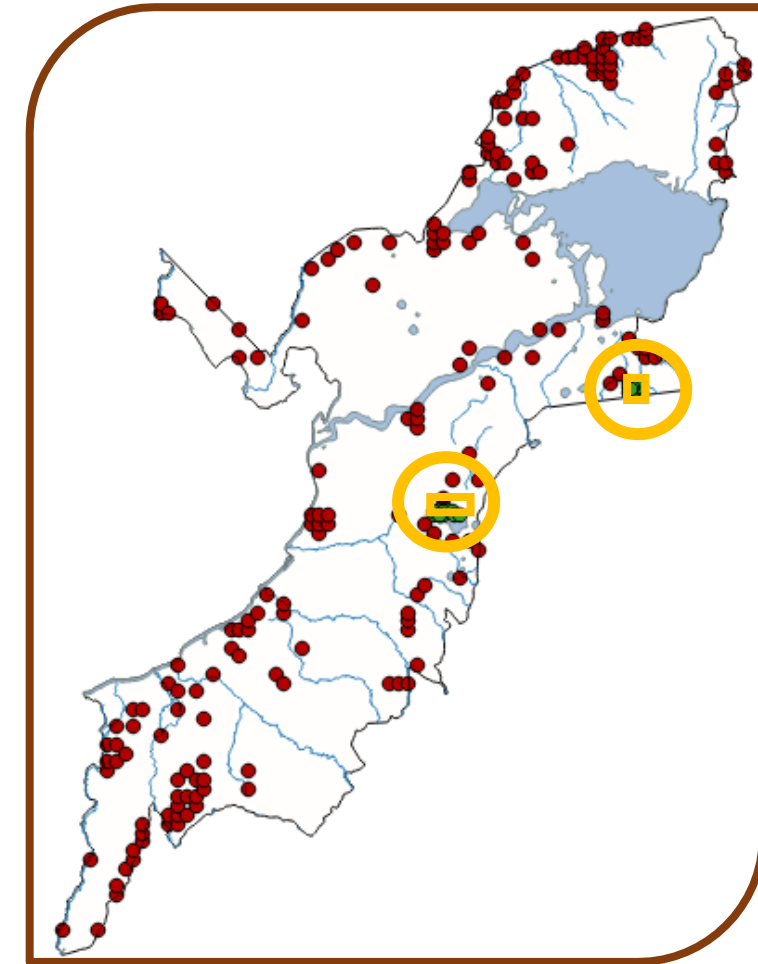


Gholami

- Two 9-sq.km areas, infrequent patrols



- Poached elephant
- 1 elephant snare roll
- 10 Antelope snares



PAWS Predicted High vs Low Risk Areas: 3 National Parks, 24 areas each, 6 months

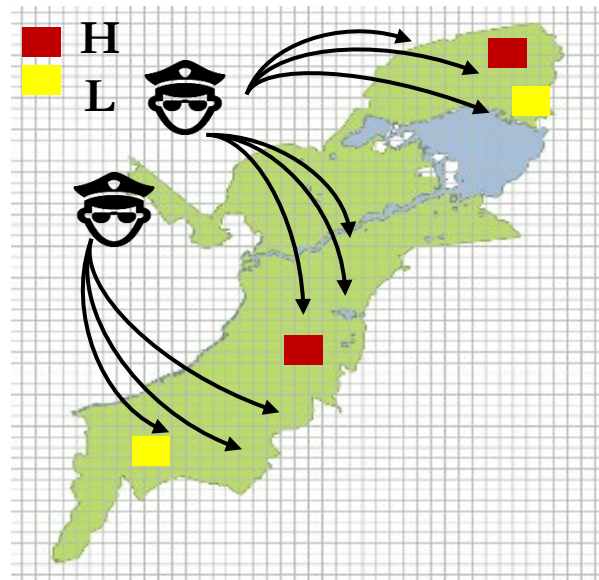
(ECML PKDD 2017, ICDE 2020)



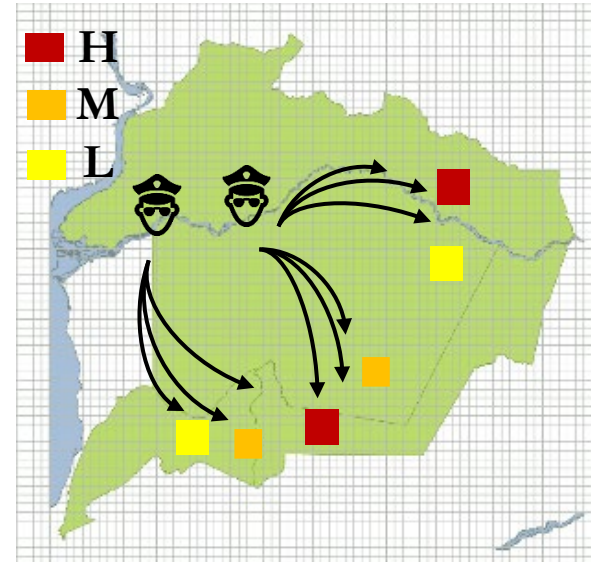
Xu



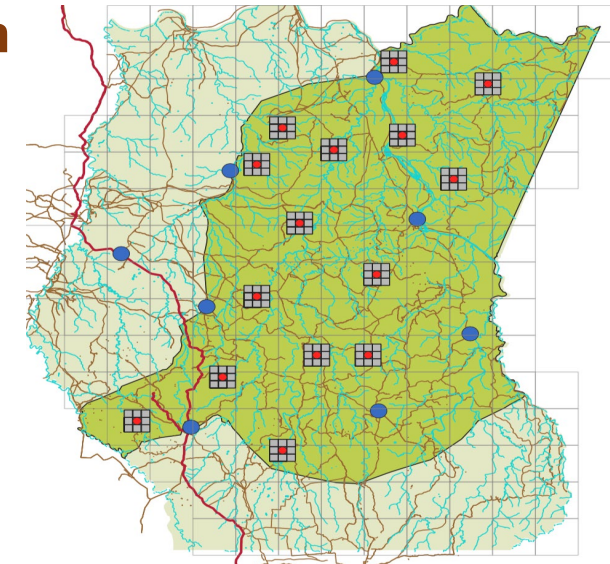
Gholami



Queen Elizabeth National Park

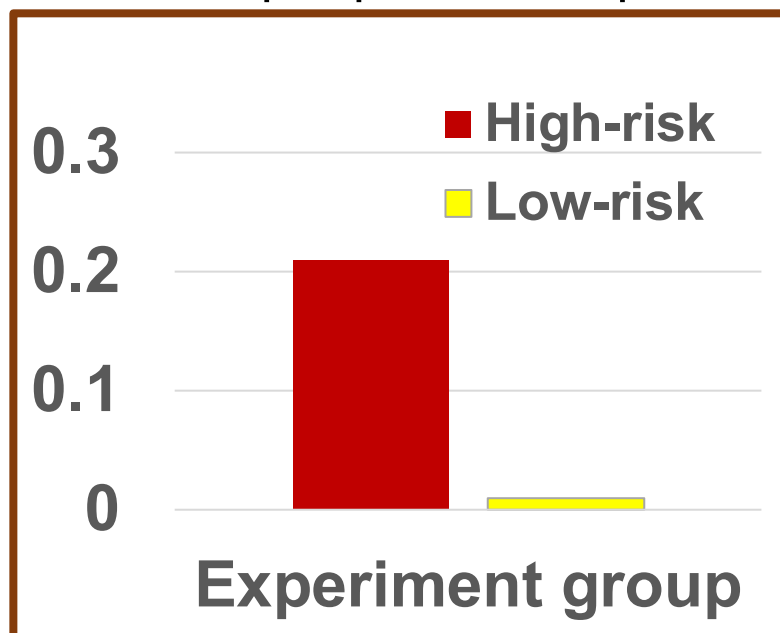


Murchison Falls National Park

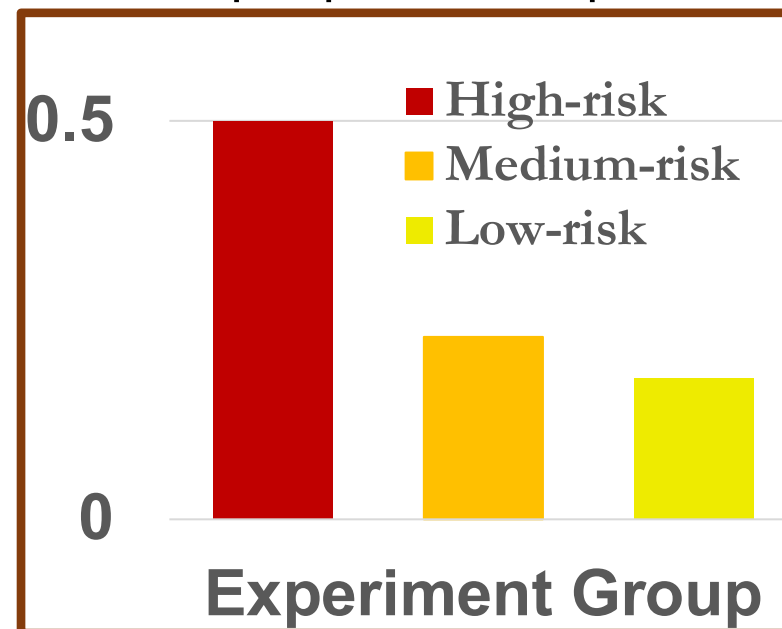


Srepok Wildlife Sanctuary

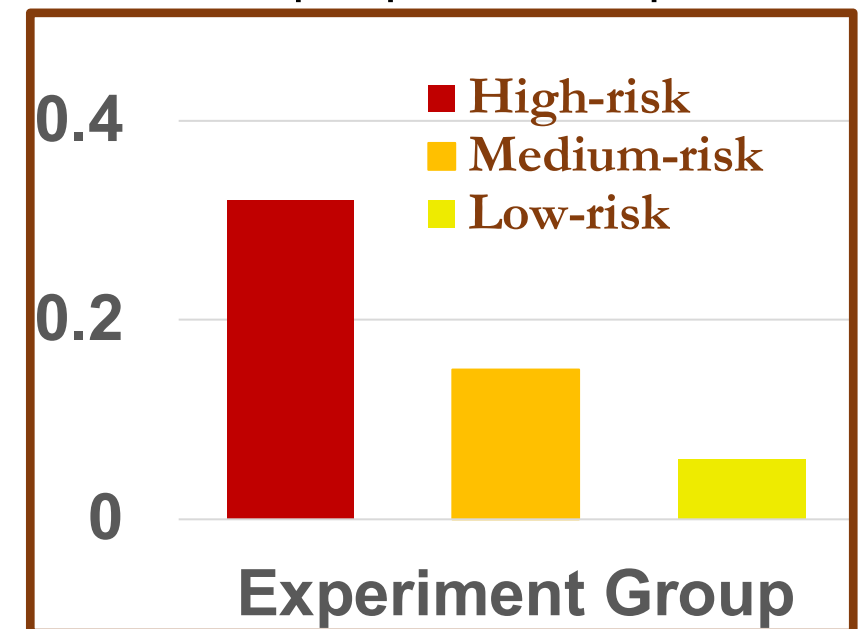
Snares per patrolled sq. KM



Snares per patrolled sq. KM



Snares per patrolled sq. KM



PAWS Real-world Deployment Cambodia: Srepok Wildlife Sanctuary

(ICDE 2020)



Xu



- *521 snares/month our tests*

VS

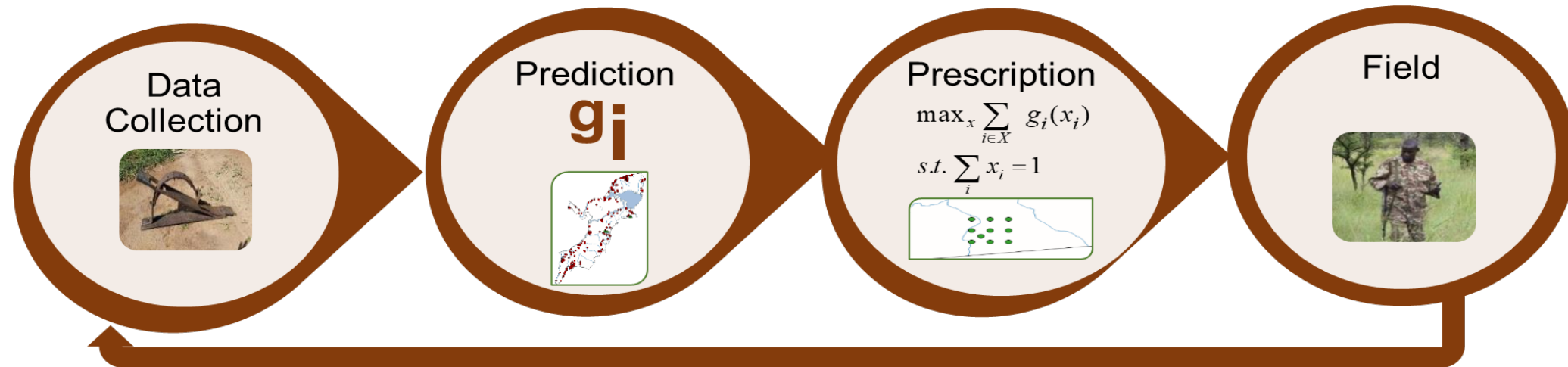
- *101 snares/month 2018*

Previous Stage-by-Stage Method:

Make Prediction as Accurate as Possible Then Plan



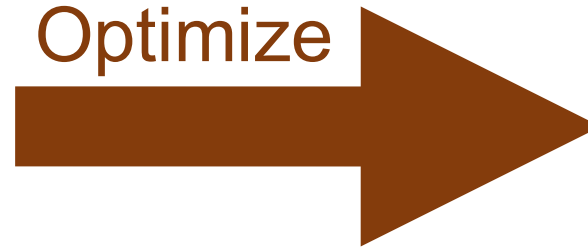
Perrault



Maximize accuracy in Adversary
target values *estimates*



Optimize



Plan patrol
Coverage



Minimize $\sum_{\{i \in T\}} q_{\text{empirical}} \log \hat{q}$

Game-Focused Learning: End-to-End Method Builds on Decision-focused Learning

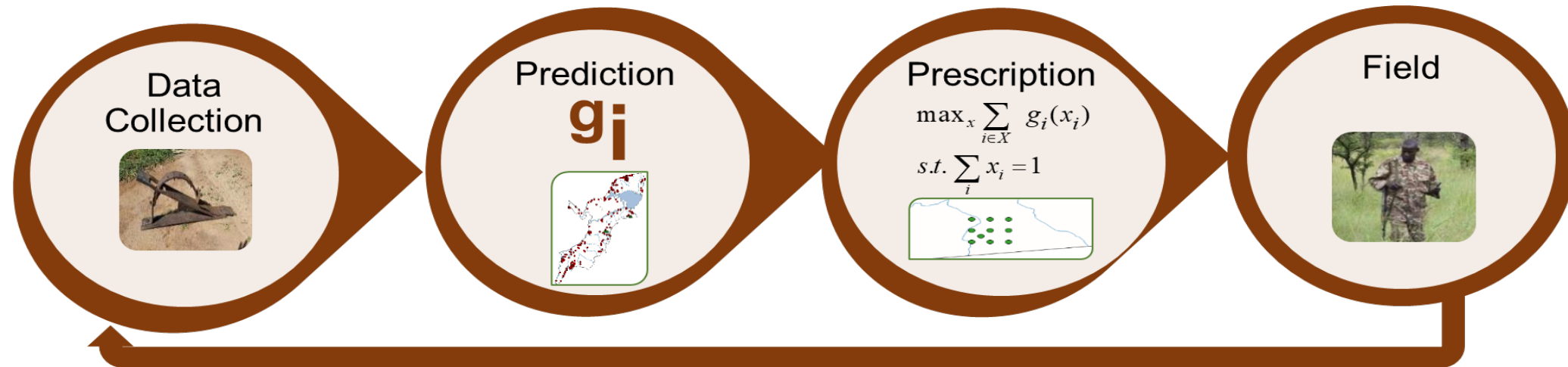
(AAAI 2019, AAAI 2020)



Perrault



Wilder



Maximize
defender expected *utility*



Optimize



Plan patrol
Coverage



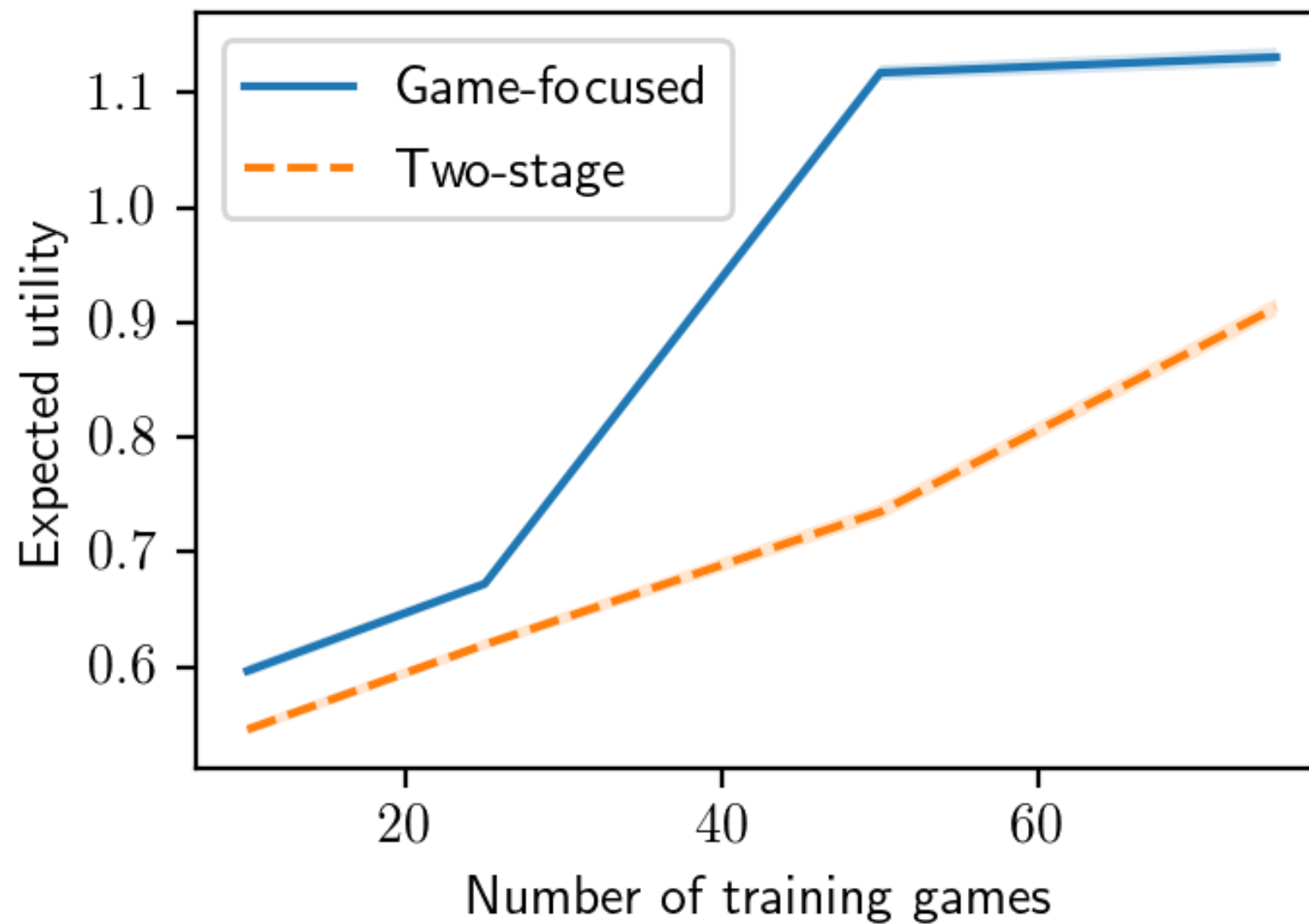
Maximize defender's
expected utility

$$\sum (1 - p_i(\hat{q})) q_{\text{empirical}}$$

Game-Focused Learning: Comparison to Two-Stage



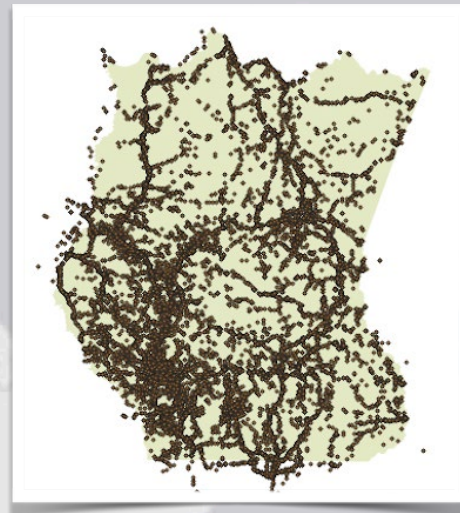
Perrault



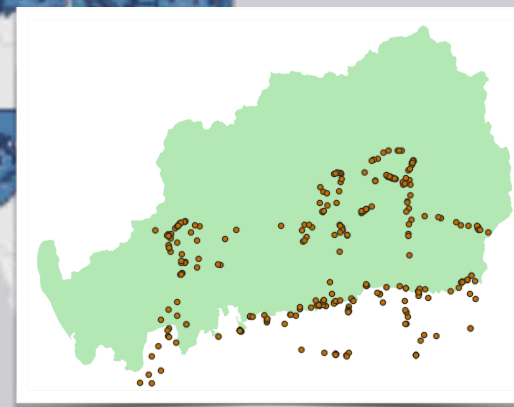
PAWS Goes Global



Xu



Srepok, Cambodia
43,269 patrol observations
2013 – 2018



Royal Belum, Malaysia
824 patrol observations
June – August 2018

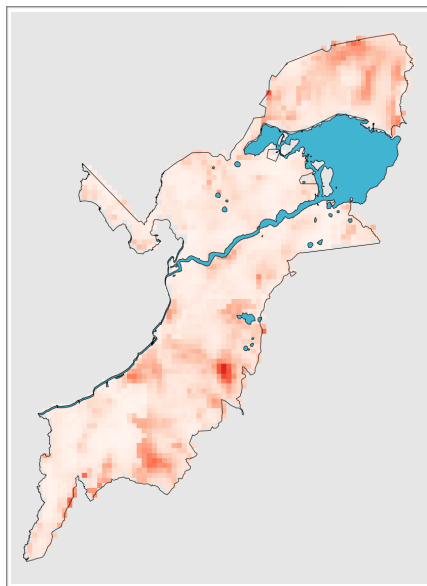
1000km
ees

The Dual Mandate



Xu

Data-rich parks: build predictive models to plan patrols

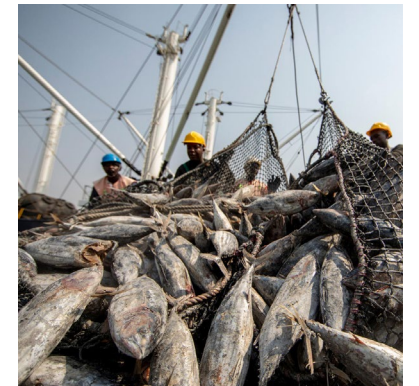


[Gholami et al., AAMAS-18,
Xu et al., ICDE-20]

exploitation

Data-scarce parks: conduct patrols to detect illegal activity and improve the predictive model

exploration





Xu

LIZARD: Multiarmed Bandit

Lipschitz Arms with Reward Decomposability

Theorem: Given N targets, Lipschitz constant L , and time horizon T , the regret bound of the LIZARD algorithm is $Reg(T) \leq O\left(L^{\frac{4}{3}}NT^{\frac{2}{3}}(\log T)^{\frac{1}{3}}\right)$:

- Input: N Targets with features, T Time Horizon
- Stochastic adversary, who places snares at targets
- Patrolling algorithm: Specify patrol effort in each target up to budget B
- Reduce regret wrt OPT , optimal patrol effort, for capturing snares

Lizard exploits decomposability, smoothness, monotonicity

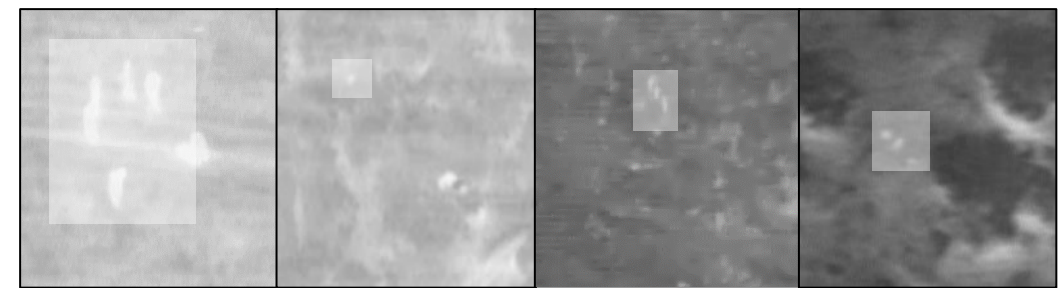
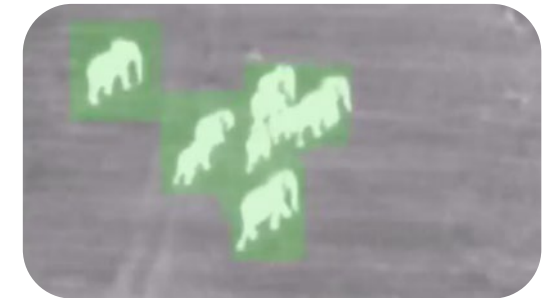
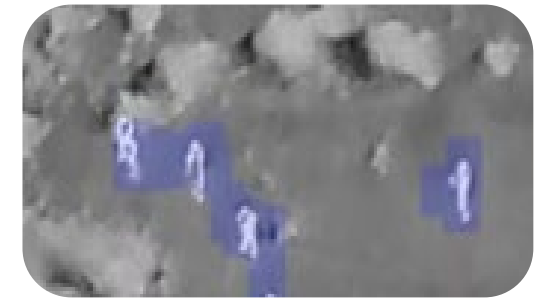
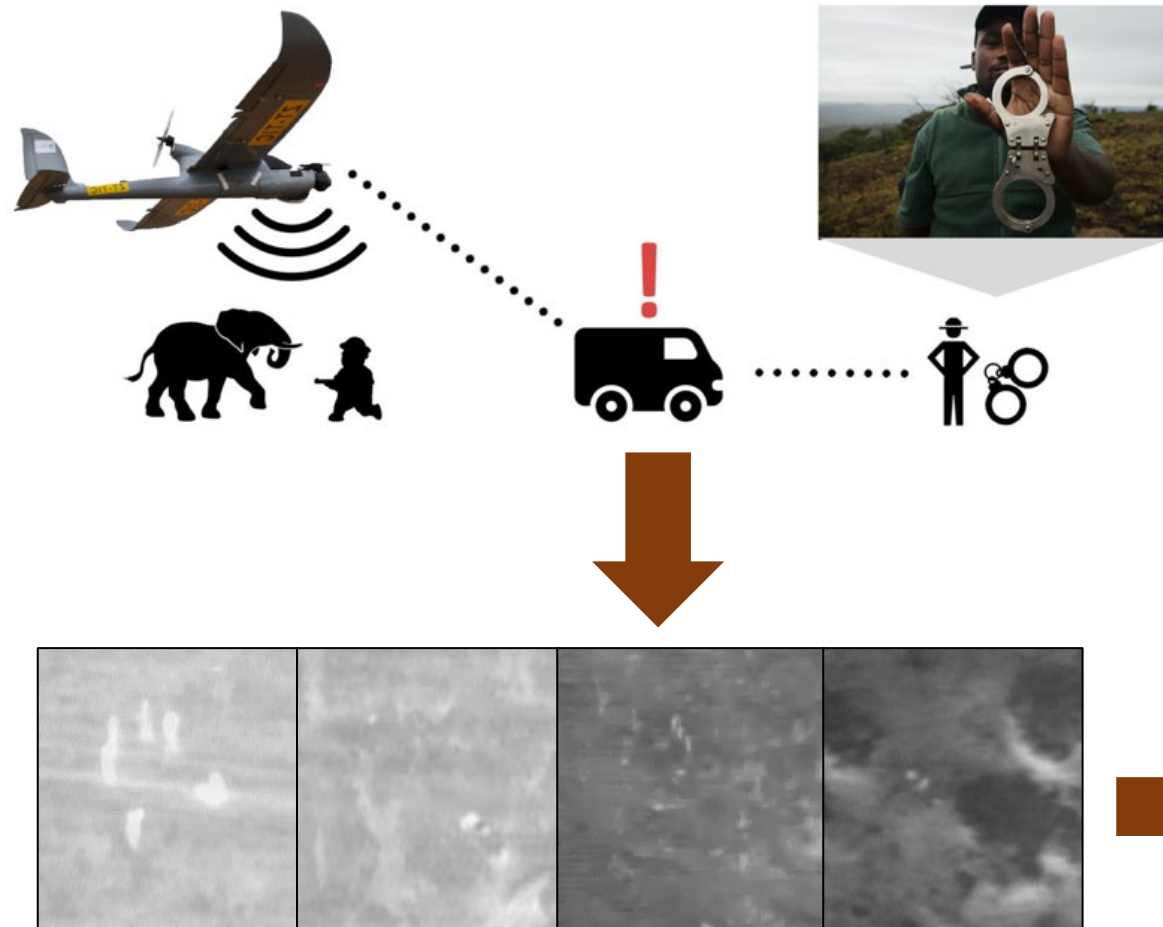


Green Security Games: Integrating Real-Time “SPOT” Information

(IAAI 2018)



Bondi



Goal: automatically find poachers

Drone Used to Inform Rangers



Xu

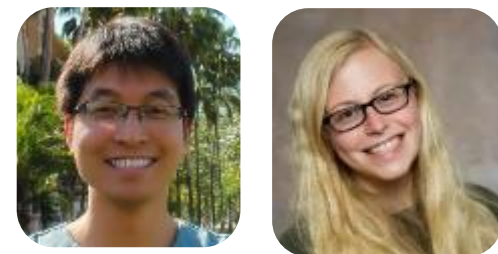


Bondi

- $Prob(ranger\ arrives) = 0.3$ [poacher may not be stopped]
- Deceptive signaling to indicate ranger is arriving



Drone Used to Inform Rangers



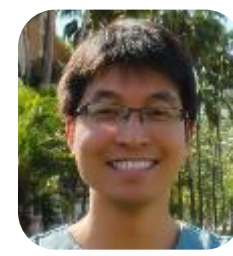
Xu

Bondi

- $Prob(\text{ranger arrives}) = 0.3$ [poacher may not be stopped]
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Drone Used to Inform Rangers



Xu



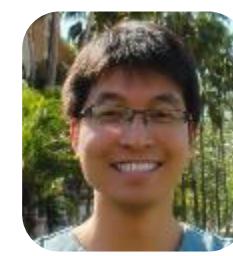
Bondi

- $Prob(ranger\ arrives) = 0.3$ [poacher may not be stopped]
- Deceptive signaling to indicate ranger is arriving
- Must be strategic in deceptive signaling



Exploiting Informational Advantage Defender Knows Pure & Mixed Strategy

(AAAI 2018, AAAI 2020)



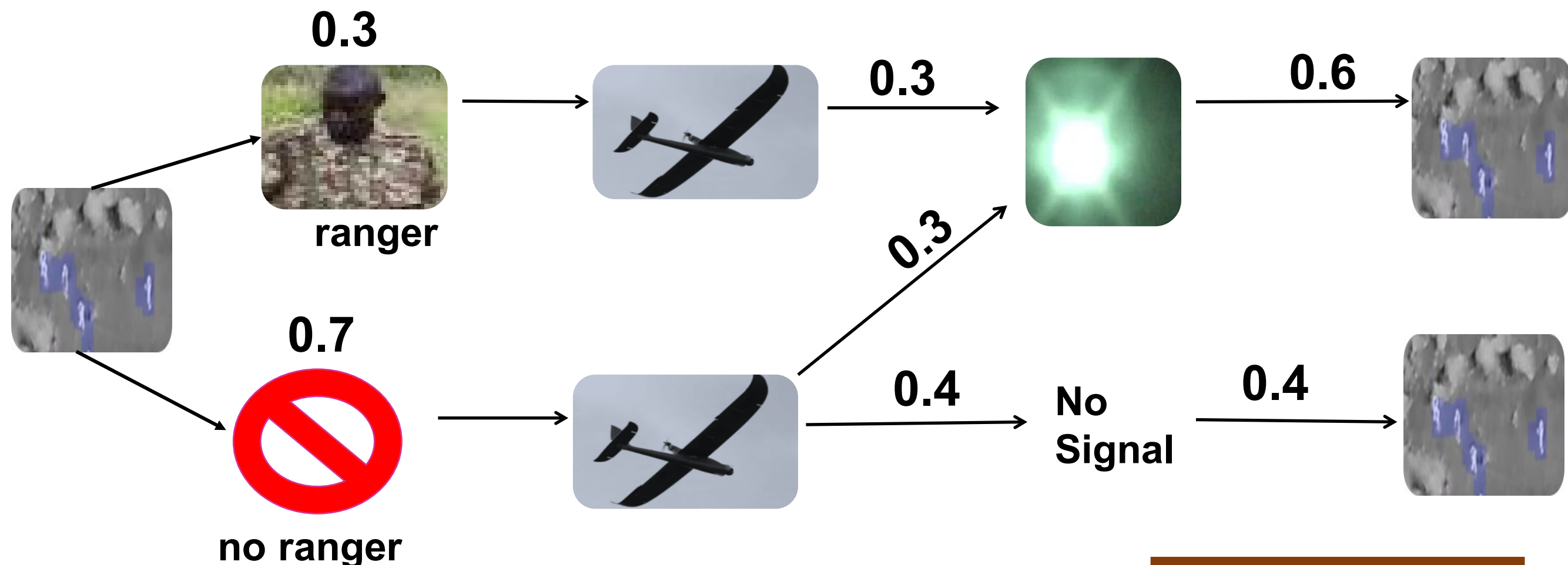
Xu



Bondi

Si-G Model: Stackelberg Security Games with Optimal Deceptive Signaling

- Poacher best interest to “believe signal” even if know 50% defender deception



PAWS GOES GLOBAL with SMART platform!!



**Protect Wildlife
800
National Parks
Around the Globe**

Also: Protect Forests, Fisheries...

Future: AI for Social Impact (AI4SG or AI4SI)



Achieving social impact & AI innovation go hand in hand



Data to deployment: Not just improving algorithms, new AI4SI evaluation



Important to step out of the lab and into the field



Embrace interdisciplinary research -- social work, conservation



Lack of data is the norm, a feature; part of the project strategy



Empower non-profits to use AI tools; avoid being gatekeepers to AI4SI tech

Key Collaborators on Papers Referenced

(In the order papers referenced)

- Eric Rice (USC)
- Nicole Immorlica (MSR)
- Yair Zick (UMASS, Amherst)
- Balaraman Ravindran (IIT-Madras)
- Amit Sharma (MSR)
- Maia Majumder (Harvard)
- Michael Mina (Harvard)
- Daniel Larremore (Colorado)
- Andy Plumptre (Cambridge)
- Rohit Singh (WWF)
- Phebe Vayanos (USC)
- Bistra Dilkina (USC)



Collaborate to realize AI's tremendous potential to
Improving society & fighting social injustice

@MilindTambe_AI

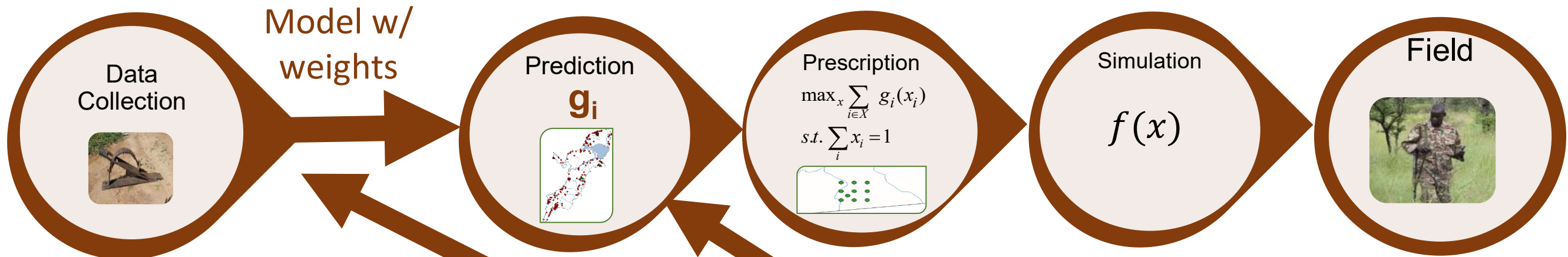
-
- The END

Another View:

Previous Two-Stage Method: Gradient Descent



Perrault Wilder

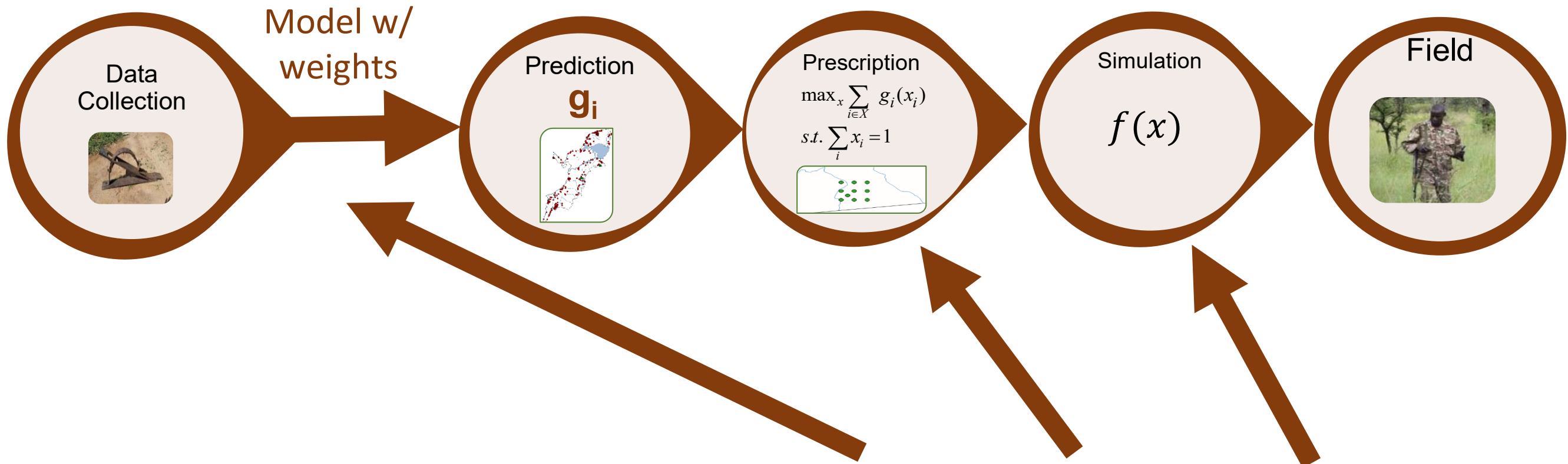


➤ Max accuracy gradient descent: $\frac{\partial \text{accuracy}}{\partial \text{weights}} = \frac{\partial \text{prediction}}{\partial \text{weights}} \frac{\partial \text{accuracy}}{\partial \text{prediction}}$

Another View: Game-Focused Learning: End-to-End Method



Perrault Wilder



➤ Game-focused gradient descent:

$$\frac{\partial \text{obj}(\text{decision})}{\partial \text{weights}} = \frac{\partial \text{prediction}}{\partial \text{weights}} \frac{\partial \text{decision}}{\partial \text{prediction}} \frac{\partial \text{obj}(\text{decision})}{\partial \text{decision}}$$